

## SYMMETRIZATION IN A PARABOLIC-ELLIPTIC SYSTEM RELATED TO CHEMOTAXIS

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**Abstract.** We study symmetrization in a nonlinear parabolic-elliptic system related to chemotaxis by using the decreasing rearrangement, and establish comparison results for solutions of an initial-boundary value problem to such a system. As an application of the comparison results, the large time behavior of the solutions is obtained.

### 1. Introduction

This paper is devoted to the study of the initial-boundary value problem to the nonlinear parabolic-elliptic system, which is denoted by  $\mathcal{P}_D(\Omega)$ ,

$$(1.1) \quad \frac{\partial u}{\partial t} = \nabla \cdot (\nabla u - \chi u \nabla v) \quad \text{in } Q_T = \Omega \times (0, T],$$

$$(1.2) \quad 0 = \Delta v - \gamma v + \alpha u \quad \text{in } Q_T,$$

$$(1.3) \quad u = 0, \quad \mathcal{B}v = 0 \quad \text{on } \Sigma_T = \partial\Omega \times (0, T],$$

$$(1.4) \quad u(\cdot, 0) = u_0 \quad \text{on } \Omega,$$

where  $\Omega$  is a bounded domain in  $R^N (N \geq 1)$  with smooth boundary  $\partial\Omega$ ,  $\mathcal{B}$  is a boundary operator such that

$$\mathcal{B}v = v|_{\partial\Omega} \text{ (Dirichlet condition) or } \mathcal{B}v = \frac{\partial v}{\partial n} \Big|_{\partial\Omega} \text{ (Neumann condition),}$$

$\chi$  and  $\alpha$  are positive numbers, and  $\gamma$  is a non-negative number such that

$$\gamma \geq 0 \text{ if } \mathcal{B}v = v|_{\partial\Omega}, \quad \gamma > 0 \text{ if } \mathcal{B}v = \frac{\partial v}{\partial n} \Big|_{\partial\Omega}.$$

The non-trivial initial function is assumed to satisfy

$$u_0 \geq 0 \text{ on } \Omega \quad \text{and} \quad u_0 \in W_0^{1,p}(\Omega) \quad (p > N).$$

The system of this type arises in the mathematical modelling of chemotaxis (aggregation of organisms sensitive to a gradient of a chemical substance), and is a simplified version of one which appeared in [14]. It is conjectured in [6, 7, 18] that there exists a solution  $(u, v)$  such that  $u$  blows up in finite time when  $N \geq 2$ . Under homogeneous Neumann boundary conditions on  $u$  and  $v$ , the global existence in time and the existence of blow-up solutions have been studied by [13, 17] in radially symmetric situations. As concerns the boundedness, [17] shows that  $(u, v)$  is bounded on  $\Omega \times [0, \infty)$  under the condition  $\alpha\chi \int_{\Omega} u_0(x)dx < 8\pi$  for the radially symmetric initial function  $u_0$  on a ball  $\Omega$  in  $R^2$ . Under homogeneous Dirichlet boundary conditions on  $u$ , rearrangement techniques are very effective in studying the boundedness of solutions  $(u, v)$  to  $\mathbf{P}_D(\Omega)$  without radially symmetric assumptions on  $u_0$ . Such techniques will give us the exponential decay of  $(u, v)$  to  $(0, 0)$  as  $t \rightarrow \infty$  under the condition  $\alpha\chi \int_{\Omega} u_0(x)dx < 8\pi$  in two dimensions.

For a solution of  $\mathbf{P}_D(\Omega)$  on  $Q_T$  we mean a function  $(u, v)$  on  $Q_T$  such that

- (i)  $u \in C([0, T]; W^{1,p}(\Omega)) \cap C^1((0, T]; L^p(\Omega))$ ,  $u(\cdot, t) \in W^{2,p}(\Omega)$  for  $0 < t \leq T$ ,
- (ii)  $v \in C((0, T]; W^{2,p}(\Omega))$ ,
- (iii)  $(u, v)$  satisfies (1.1)–(1.4).

A function  $(u, v)$  on  $Q = \Omega \times (0, \infty)$  is said to be a global solution of  $\mathbf{P}_D(\Omega)$  if  $(u, v)$  is a solution of  $\mathbf{P}_D(\Omega)$  on  $Q_T$  for any  $T > 0$ .

In Sect.2 it will be shown that there exists uniquely a non-negative solution  $(u, v)$  of  $\mathbf{P}_D(\Omega)$  on  $Q_T$  for some  $T > 0$ , which becomes a classical solution on  $Q_T$ . By using the strong maximum principle, we see that

$$u(x, t) > 0 \quad \text{and} \quad v(x, t) > 0 \quad \text{on } Q_T.$$

In Sect.3 we shall compare the solution  $(u, v)$  of  $\mathbf{P}_D(\Omega)$  with the solution  $(U, V)$  of the following symmetrized problem, which is denoted by  $\mathbf{SP}_D(\tilde{\Omega})$ ,

$$(1.5) \quad \frac{\partial U}{\partial t} = \nabla \cdot (\nabla U - \chi U \nabla V) \quad \text{in } \tilde{Q}_T = \tilde{\Omega} \times (0, T],$$

$$(1.6) \quad 0 = \Delta V + \alpha U \quad \text{in } \tilde{Q}_T,$$

$$(1.7) \quad U = V = 0 \quad \text{on } \partial\tilde{\Omega} \times (0, T],$$

$$(1.8) \quad U(\cdot, 0) = \tilde{u}_0 \quad \text{on } \tilde{\Omega},$$

where  $\tilde{\Omega}$  is the ball in  $R^N$  centered at the origin with the same measure as  $\Omega$ ,  $\partial\tilde{\Omega}$  is the boundary of  $\tilde{\Omega}$  and  $\tilde{u}_0$  is the symmetric rearrangement of  $u_0$  defined in Sect. 3. By the condition on  $u_0$ ,

$$\tilde{u}_0 \geq 0 \text{ on } \tilde{\Omega} \quad \text{and} \quad \tilde{u}_0 \in W_0^{1,p}(\tilde{\Omega}).$$

A function  $(U, V)$  on  $\tilde{Q}_T$  is called a solution of  $\mathbf{SP}_D(\tilde{\Omega})$  if  $(U, V)$  satisfies the following :

- (i)  $U \in C([0, T]; W^{1,p}(\tilde{\Omega})) \cap C^1((0, T]; L^p(\tilde{\Omega}))$ ,  $U(\cdot, t) \in W^{2,p}(\tilde{\Omega})$  for  $0 < t \leq T$ ,
- (ii)  $V \in C((0, T]; W^{2,p}(\tilde{\Omega}))$ ,
- (iii)  $(U, V)$  satisfies (1.5)–(1.8).

There exists a unique solution  $(U, V)$  of  $\mathbf{SP}_D(\tilde{\Omega})$  on  $\tilde{Q}_T$  for some  $T > 0$ , which satisfies

- (i)  $U(x, t) \geq 0$  and  $V(x, t) \geq 0$  on  $\tilde{Q}_T$ ,
- (ii)  $U$  and  $V$  are radially symmetric in  $x \in \tilde{\Omega}$  and decrease along the radii.

The purpose in Sect.3 is to show the integral comparison

$$(1.9) \quad \int_0^s u^*(\sigma, t) d\sigma \leq \int_0^s U^*(\sigma, t) d\sigma \quad \text{for } s \in [0, |\Omega|].$$

Here  $u^*(\cdot, t)$  ( resp.  $U^*(\cdot, t)$  ) is the decreasing rearrangement of  $u(\cdot, t)$  ( resp.  $U(\cdot, t)$  ) with respect to  $x$  defined in Sect. 3. Then the comparison of  $L^r$ -norms ( $1 \leq r \leq \infty$ ) of  $u$  and  $U$

$$(1.10) \quad \|u(\cdot, t)\|_{L^r(\Omega)} \leq \|U(\cdot, t)\|_{L^r(\tilde{\Omega})}$$

can be derived from (1.9). The integral comparison was first proved by [4] for strong solutions to linear parabolic equations and by [16] for weak solutions. For nonlinear parabolic equations we refer to [2, 3, 5, 9, 10, 23].

In Sect.4 it is shown that there is no stationary solution to  $\mathbf{P}_D(\Omega)$  except a trivial stationary solution. This means that the structure of stationary solutions to (1.1)–(1.2) under Dirichlet boundary conditions on  $u$  is quite different from that under Neumann boundary conditions on  $u$  (see [19]). As an application of (1.10), we shall show the global existence of non-negative solution  $(u, v)$  to the problem  $\mathbf{P}_D(\Omega)$  and the exponential decay of  $(u, v)$  to  $(0, 0)$  as  $t \rightarrow \infty$  under each of the following conditions.

$$(C1) \quad N = 1,$$

$$(C2) \quad N = 2 \quad \text{and} \quad \alpha\chi \int_{\Omega} u_0(x)dx < 8\pi,$$

$$(C3) \quad N \geq 3 \quad \text{and} \quad \alpha\chi \|u_0\|_{L^N(\Omega)} < N\kappa_N^{\frac{2}{N}} |\Omega|^{-\frac{1}{N}},$$

where  $\kappa_N$  is the volume of the unit ball in  $R^N$ .

## 2. Local existence in time

Let  $(u, v)$  be a solution of  $\mathbf{P}_D(\Omega)$  on  $Q_T$ . Since  $p > N$ ,

$$(2.1) \quad W^{1,p}(\Omega) \subset C(\bar{\Omega})$$

with continuous inclusion (see [11]). By  $u \in C([0, T]; W^{1,p}(\Omega))$  and (2.1),

$$(2.2) \quad \sup_{0 \leq t \leq T} \|u(\cdot, t)\|_{L^\infty(\Omega)} \leq \text{Const.} \sup_{0 \leq t \leq T} \|u(\cdot, t)\|_{W^{1,p}(\Omega)} < \infty.$$

Using  $L^r$ -estimates ( $1 < r < \infty$ ) for elliptic equations (see [21]), we have

$$\|v(\cdot, t)\|_{W^{2,r}(\Omega)} \leq \text{Const.} \|u(\cdot, t)\|_{L^r(\Omega)} \quad \text{for } 0 < t \leq T,$$

which together with (2.1) implies that

$$(2.3) \quad \sup_{0 < t \leq T} \left( \|v(\cdot, t)\|_{L^\infty(\Omega)} + \|\nabla v(\cdot, t)\|_{L^\infty(\Omega)} \right) \leq \text{Const.} \sup_{0 \leq t \leq T} \|u(\cdot, t)\|_{L^p(\Omega)} < \infty.$$

We first show the uniqueness of solutions to  $\mathbf{P}_D(\Omega)$  on  $Q_T$ .

**Lemma 1.** *The uniqueness holds for the problem  $\mathbf{P}_D(\Omega)$  on  $Q_T$ .*

*Proof.* Let  $(u_1, v_1)$  and  $(u_2, v_2)$  be the solutions of  $\mathbf{P}_D(\Omega)$  on  $Q_T$  with the same initial function  $u_0 \in W_0^{1,p}(\Omega)$ . Put  $a = u_1 - u_2$  and  $b = v_1 - v_2$ , which satisfy

$$(2.4) \quad \begin{cases} \frac{\partial a}{\partial t} = \Delta a - \chi \nabla \cdot (a \nabla v_1 + u_2 \nabla b) & \text{in } Q_T, \\ 0 = \Delta b - \gamma b + \alpha a & \text{in } Q_T, \end{cases}$$

and the initial-boundary conditions

$$a = 0, \quad \mathcal{B}b = 0 \text{ on } \Sigma_T \quad \text{and} \quad a(\cdot, 0) = 0 \text{ on } \Omega.$$

Multiplying the first equation in (2.4) by  $|a|^{p-2}a$  and integrating over  $\Omega$ , we have

$$(2.5) \quad \begin{aligned} & \frac{1}{p} \frac{d}{dt} \int_{\Omega} |a|^p dx + (p-1) \int_{\Omega} |a|^{p-2} |\nabla a|^2 dx \\ & = \chi(p-1) \int_{\Omega} |a|^{p-2} a \nabla v_1 \cdot \nabla a dx + \chi(p-1) \int_{\Omega} |a|^{p-2} u_2 \nabla b \cdot \nabla a dx. \end{aligned}$$

By using (2.3), the first term in the right-hand side of (2.5) is estimated as

$$\begin{aligned} & \chi(p-1) \int_{\Omega} |a|^{p-2} a \nabla v_1 \cdot \nabla a dx \\ & \leq \chi(p-1) \|\nabla v_1\|_{L^\infty(\Omega)} \left( \int_{\Omega} |a|^p dx \right)^{\frac{1}{2}} \left( \int_{\Omega} |a|^{p-2} |\nabla a|^2 dx \right)^{\frac{1}{2}} \\ & \leq \frac{p-1}{4} \int_{\Omega} |a|^{p-2} |\nabla a|^2 dx + \text{Const.} \int_{\Omega} |a|^p dx. \end{aligned}$$

The second term in the right-hand side of (2.5) is estimated as

$$\begin{aligned} & \chi(p-1) \int_{\Omega} |a|^{p-2} u_2 \nabla b \cdot \nabla a dx \\ & \leq \chi(p-1) \|u_2\|_{L^\infty(\Omega)} \left( \int_{\Omega} |a|^{p-2} |\nabla a|^2 dx \right)^{\frac{1}{2}} \left( \int_{\Omega} |a|^{p-2} |\nabla b|^2 dx \right)^{\frac{1}{2}} \\ & \leq \frac{p-1}{4} \int_{\Omega} |a|^{p-2} |\nabla a|^2 dx + \text{Const.} \int_{\Omega} |a|^{p-2} |\nabla b|^2 dx. \end{aligned}$$

By Hölder's inequality and  $\|\nabla b\|_{L^p(\Omega)} \leq \text{Const.} \|a\|_{L^p(\Omega)}$ ,

$$\int_{\Omega} |a|^{p-2} |\nabla b|^2 dx \leq \left( \int_{\Omega} |a|^p dx \right)^{\frac{p-2}{p}} \left( \int_{\Omega} |\nabla b|^p dx \right)^{\frac{2}{p}} \leq \text{Const.} \int_{\Omega} |a|^p dx.$$

Combining (2.5) with these inequalities obtained above, we obtain

$$(2.6) \quad \frac{1}{p} \frac{d}{dt} \int_{\Omega} |a|^p dx + \frac{p-1}{2} \int_{\Omega} |a|^{p-2} |\nabla a|^2 dx \leq \text{Const.} \int_{\Omega} |a|^p dx \quad \text{for } 0 < t \leq T.$$

Since  $a(x, 0) = 0$  on  $\Omega$ , (2.6) yields that

$$\int_{\Omega} |a|^p(x, t) dx = 0 \quad \text{for } 0 \leq t \leq T.$$

Hence, we have  $a(x, t) = 0$  on  $Q_T$  and then  $b(x, t) = 0$  on  $Q_T$ , which implies the uniqueness of solutions to  $\mathbf{P}_D(\Omega)$  on  $Q_T$ .  $\square$

**Lemma 2.** *Let  $(u, v)$  be a solution of  $\mathbf{P}_D(\Omega)$  on  $Q_T$  with the non-negative initial function  $u_0$ . Then  $u(x, t) \geq 0$  and  $v(x, t) \geq 0$  on  $Q_T$ .*

*Proof.* We note that  $u_-(\cdot, t) \in W_0^{1,p}(\Omega)$ , where  $u_-(x, t) = -\min\{u(x, t), 0\}$ . Multiply (1.1) by  $(u_-)^{p-2}u_-$  and integrate over  $\Omega$  to get

$$\frac{1}{p} \frac{d}{dt} \int_{\Omega} (u_-)^p dx + (p-1) \int_{\Omega} (u_-)^{p-2} |\nabla u_-|^2 dx = \chi(p-1) \int_{\Omega} (u_-)^{p-1} \nabla u_- \cdot \nabla v dx.$$

The right-hand side of this relation is estimated as

$$\begin{aligned} & \chi(p-1) \int_{\Omega} (u_-)^{p-1} \nabla u_- \cdot \nabla v dx \\ & \leq \chi(p-1) \|\nabla v\|_{L^\infty(\Omega)} \left\{ \int_{\Omega} (u_-)^p dx \right\}^{\frac{1}{2}} \left\{ \int_{\Omega} (u_-)^{p-2} |\nabla u_-|^2 dx \right\}^{\frac{1}{2}} \\ & \leq \frac{p-1}{2} \int_{\Omega} (u_-)^{p-2} |\nabla u_-|^2 dx + \text{Const.} \int_{\Omega} (u_-)^p dx. \end{aligned}$$

Hence,

$$(2.7) \quad \frac{d}{dt} \int_{\Omega} (u_-)^p dx \leq \text{Const.} \int_{\Omega} (u_-)^p dx \quad \text{for } 0 < t \leq T.$$

Since  $u_-(x, 0) = 0$  on  $\Omega$ , it follows from (2.7) that

$$\int_{\Omega} (u_-)^p(x, t) dx = 0 \quad \text{for } 0 < t \leq T,$$

which implies that  $u_-(x, t) = 0$  on  $Q_T$ . Therefore,  $u(x, t) \geq 0$  on  $Q_T$ , and then  $v(x, t) \geq 0$  on  $Q_T$  by the maximum principle for  $-\Delta v + \gamma v = \alpha u$  in  $\Omega$  with  $\mathcal{B}v = 0$  on  $\partial\Omega$ .  $\square$

In order to show the local existence of solutions to  $\mathbf{P}_D(\Omega)$ , we apply abstract results in [12] to Cauchy problem for semilinear equations in a Banach space.

Let  $A_D$  and  $A_B$  be closed operators in  $L^p(\Omega)$  defined by

$$\begin{aligned} A_D u &= -\Delta u & \text{for } u \in D(A_D) &= \{u \in W^{2,p}(\Omega); u = 0 \text{ on } \partial\Omega\}, \\ A_B u &= -\Delta u & \text{for } u \in D(A_B) &= \{u \in W^{2,p}(\Omega); \mathcal{B}u = 0 \text{ on } \partial\Omega\}. \end{aligned}$$

$A_D$  and  $A_B$  are sectorial operators in  $L^p(\Omega)$ , and

$$\sigma(A_D) \subset \{z \in \mathbb{C}; \operatorname{Re}(z) > 0\}, \quad \sigma(A_B) \subset \{z \in \mathbb{C}; \operatorname{Re}(z) \geq 0\},$$

where  $\sigma(A_D)$  and  $\sigma(A_B)$  stand for the spectrums of  $A_D$  and  $A_B$ , respectively (see [21]). The fractional powers  $A_D^\gamma$  of  $A_D$  is defined, and in [12, 22]  $D(A_D^{1/2})$  is characterized by

$$D(A_D^{1/2}) = W_0^{1,p}(\Omega).$$

Since  $v = \alpha(\gamma + A_B)^{-1}u$  for a solution  $(u, v)$  to  $\mathbb{P}_D(\Omega)$ , we rewrite  $\mathbb{P}_D(\Omega)$  on  $Q_T$  as the following Cauchy problem in  $L^p(\Omega)$

$$(CP) \quad \begin{cases} \frac{du}{dt}(t) + A_D u(t) = f(u(t)), & 0 < t \leq T, \\ u(0) = u_0, \end{cases}$$

where

$$f(u) = -\alpha\chi \left\{ \nabla(\gamma + A_B)^{-1}u \cdot \nabla u + \gamma u(\gamma + A_B)^{-1}u - u^2 \right\}.$$

To deal with the nonlinear term  $f(u)$  we need the following lemma (see [11]).

**Lemma 3.** *Let  $1 < q < \infty$ . For  $0 \leq \gamma \leq 1$ ,*

$$\begin{aligned} D(A_D^\gamma) &\subset W^{1,q^*}(\Omega) & \text{when } 1 - N/q^* < 2\gamma - N/q, \quad q^* \geq q, \\ D(A_D^\gamma) &\subset C^v(\bar{\Omega}) & \text{when } 0 \leq v < 2\gamma - N/q, \end{aligned}$$

where each imbedding is continuous.

We note  $p > N$  and take  $\gamma$  such that

$$\frac{N}{4p} + \frac{1}{2} < \gamma < 1.$$

Since  $1 - N/(2p) < 2\gamma - N/p$ , Lemma 3 implies that

$$\|u\|_{W^{1,2p}(\Omega)} \leq \text{Const.} \|A_D^\gamma u\|_{L^p(\Omega)} \quad \text{for } u \in D(A_D^\gamma).$$

By using Hölder's inequality and the inequality

$$\|(\gamma + A_B)^{-1}u\|_{W^{2,2p}(\Omega)} \leq \text{Const.} \|u\|_{L^{2p}(\Omega)} \quad \text{for } u \in L^{2p}(\Omega),$$

we have

$$\|f(v) - f(w)\|_{L^p(\Omega)} \leq \text{Const.} \left( \|v\|_{W^{1,2p}(\Omega)} + \|w\|_{W^{1,2p}(\Omega)} \right) \|v - w\|_{W^{1,2p}(\Omega)}.$$

Hence,

$$\|f(v) - f(w)\|_{L^p(\Omega)} \leq \text{Const.} \left( \|A_D^\gamma v\|_{L^p(\Omega)} + \|A_D^\gamma w\|_{L^p(\Omega)} \right) \|A_D^\gamma(v - w)\|_{L^p(\Omega)}$$

for  $v, w \in D(A_D^\gamma)$ .

**Theorem 1.** (i). *For an initial function  $u_0 \in W_0^{1,p}(\Omega)$  there exists a positive number  $T$  such that  $\mathbb{P}_D(\Omega)$  has a unique solution  $(u, v)$  on  $Q_T$ , which becomes a classical solution.*

(ii). *If the non-trivial initial function  $u_0$  is non-negative on  $\Omega$ , then  $u(x, t) > 0$  and  $v(x, t) > 0$  on  $Q_T$ .*

(iii). *Let  $T_{max}$  be a maximal existence time of  $(u, v)$ . If  $\|u(\cdot, t)\|_{L^p(\Omega)} \leq \text{Const.}$  on  $(0, T_{max})$ , then  $T_{max} = \infty$  and  $\|u(\cdot, t)\|_{L^\infty(\Omega)} \leq \text{Const.}$  on  $(0, \infty)$ .*

*Proof.* We apply Theorems 1 and 2 in [12] to get the local existence of solution to (CP). For  $u_0 \in D(A_D^{1/2}) = W_0^{1,p}(\Omega)$  there exists a positive number  $T$  such that (CP) has a solution  $u$  on  $[0, T]$  satisfying

$$u \in C([0, T]; D(A_D^{1/2})) \cap C^1((0, T]; L^p(\Omega)), \quad u(t) \in D(A_D) \text{ for } 0 < t \leq T.$$

By putting  $v = \alpha(\gamma + A_B)^{-1}u$ ,  $(u, v)$  becomes the unique solution of  $\mathbb{P}_D(\Omega)$  on  $Q_T$ . As concerns classical solution of  $\mathbb{P}_D(\Omega)$ , by Lemma 3 and the regularity theory for elliptic equations, similar arguments in [11, 12] yield that  $u \in C(\bar{\Omega} \times [0, T]) \cap C^{2,1}(\bar{\Omega} \times (0, T])$ ,  $v(\cdot, t) \in C^2(\bar{\Omega})$  and  $(u, v)$  is a classical solution of  $\mathbb{P}_D(\Omega)$  on  $Q_T$ .

Note that  $|\nabla v|$  and  $\Delta v$  are bounded on  $Q_T$  by (2.2), (2.3) and (1.2). If  $u_0 \geq 0$  on  $Q_T$ , then  $u(x, t) \geq 0$  and  $v(x, t) \geq 0$  on  $Q_T$  by Lemma 2. Since  $u$  is a classical solution of the problem

$$\begin{cases} \frac{\partial u}{\partial t} = \Delta u - \chi \nabla v \cdot \nabla u - \chi(\Delta v)u & \text{in } Q_T, \\ u = 0 & \text{on } \Sigma_T, \quad u(x, 0) = u_0(x) & \text{on } \Omega, \end{cases}$$

the strong maximum principle yields that

$$u(x, t) > 0 \quad \text{and} \quad v(x, t) > 0 \quad \text{on } Q_T.$$

Let us prove the assertion (iii). By  $\|u(\cdot, t)\|_{L^p(\Omega)} \leq \text{Const.}$  on  $(0, T_{max})$  and (2.3),

$$\|\nabla v(\cdot, t)\|_{L^\infty(\Omega)} \leq \text{Const.} \quad \text{on } (0, T_{max}).$$

Hence, by Proposition A.2 we get

$$(2.8) \quad \|u(\cdot, t)\|_{L^\infty(\Omega)} \leq \text{Const.} \quad \text{on } (0, T_{max}).$$

Assume  $T_{max} < \infty$ . For fixed  $t_0 \in (0, T_{max})$ ,  $u(t_0) \in D(A_D^\gamma)$ . For  $t \in (t_0, T_{max})$ ,  $u(t)$  is rewritten as

$$u(t) = e^{-(t-t_0)A_D} u(t_0) + \int_{t_0}^t e^{-(t-s)A_D} f(u(s)) ds,$$

where  $\{e^{-tA_D}\}_{t \geq 0}$  is an analytic semi-group generated by  $-A_D$  in  $L^p(\Omega)$ . Using (2.3) and (2.8), we see that

$$\|f(u(t))\|_{L^p(\Omega)} \leq \text{Const.} \left( \|A_D^\gamma u(t)\|_{L^p(\Omega)} + 1 \right) \quad \text{on } [t_0, T_{max}).$$

By a similar way in the proof of Corollary 3.3.5 in [11], we have

$$\|A_D^\gamma u(t)\|_{L^p(\Omega)} \leq \text{Const.} \quad \text{on } [t_0, T_{max}),$$

which implies that

$$\|f(u(t))\|_{L^p(\Omega)} \leq \text{Const.} \quad \text{on } [t_0, T_{max}).$$

A similar argument in Theorem 3.3.4 in [11] gives that  $\lim_{t \rightarrow T_{max}} u(t)$  exists in  $D(A_D^\gamma)$ . Hence, the solution  $u(t)$  of (CP) can be extended beyond time  $T_{max}$ , which contradicts maximality of  $T_{max}$ .  $\square$

We remark that the same results as in Theorem 1 hold to the problem  $\text{SP}_D(\tilde{\Omega})$  by using similar arguments. The solution  $(U, V)$  of  $\text{SP}_D(\tilde{\Omega})$  is radially symmetric in  $x \in \tilde{\Omega}$  by the uniqueness of the solution and the symmetry of the problem.

### 3. Rearrangement and integral comparison

For a measurable set  $E$  in  $R^N$ , we denote  $|E|$  its Lebesgue measure. Let  $f$  be a measurable function on  $\Omega$ . For simplicity we denote a subset  $\{x \in \Omega; f(x) > s\}$  in  $R^N$  by  $\{f > s\}$ . Let us put  $\Omega^* = (0, |\Omega|)$ . The decreasing rearrangement  $f^*$  of  $f$  is the function from  $\overline{\Omega^*}$  into  $[-\infty, \infty]$  defined by

$$f^*(s) = \begin{cases} \inf\{\tau; |\{f > \tau\}| \leq s\} & \text{if } 0 \leq s < |\Omega|, \\ \text{ess inf}\{f(x); x \in \Omega\} & \text{if } s = |\Omega|. \end{cases}$$

$f^*$  is non-increasing and right-continuous, and satisfies

$$f^*(0) = \text{ess sup}\{f(x); x \in \Omega\}.$$

The symmetric rearrangement  $\tilde{f}$  of  $f$  on  $\tilde{\Omega}$  is defined by

$$\tilde{f}(x) = f^*(\kappa_N |x|^N) \quad (x \in \tilde{\Omega}).$$

Some basic facts about rearrangement are as follows (see [4, 8, 15]):

(i) For every Borel measurable function  $F$  from  $R$  to  $R^+$ ,

$$\int_{\Omega} F(f) dx = \int_{\tilde{\Omega}} F(\tilde{f}) dx = \int_{\Omega^*} F(f^*) ds.$$

In particular, If  $f \in L^r(\Omega)$  ( $1 \leq r \leq \infty$ ), then

$$\|f\|_{L^r(\Omega)} = \|\tilde{f}\|_{L^r(\tilde{\Omega})} = \|f^*\|_{L^r(\Omega^*)}.$$

(ii) For  $f \in L^r(\Omega)$  and  $g \in L^q(\Omega)$  ( $1 \leq r \leq \infty$ ,  $1/r + 1/q = 1$ ),

$$\int_{\Omega} f g dx \leq \int_{\Omega^*} f^* g^* ds.$$

(iii) If  $f \in W_0^{1,r}(\Omega)$  ( $1 \leq r \leq \infty$ ) and  $f \geq 0$  on  $\Omega$ , then  $\tilde{f} \in W_0^{1,r}(\tilde{\Omega})$  and

$$\|\nabla \tilde{f}\|_{L^r(\tilde{\Omega})} \leq \|\nabla f\|_{L^r(\Omega)}.$$

We remark that if  $f \in W_0^{1,r}(\Omega)$  ( $1 \leq r \leq \infty$ ) and  $f \geq 0$  on  $\Omega$ , then  $f^* \in W^{1,r}(\delta, |\Omega|)$  for every  $\delta$  and  $f^* \in C(\Omega^*)$ .

Let  $(u, v)$  be a non-negative solution of  $\text{P}_D(\Omega)$  on  $Q_T$ . We indicate with  $\mu$  the distribution function of  $u$  with respect to  $x$  defined by

$$\mu(s) = |\{u(\cdot, t) > s\}|,$$

which is a function of  $s$  and  $t$ . We consider the decreasing rearrangement of  $u(\cdot, t)$  with respect to  $x$  as

$$u^*(s, t) = u(\cdot, t)^*(s) = \inf\{\tau; \mu(\tau) \leq s\}$$

and the symmetric rearrangement  $\tilde{u}(\cdot, t)$  of  $u(\cdot, t)$  by

$$\tilde{u}(x, t) = u^*(\kappa_N |x|^N, t) \quad (x \in \tilde{\Omega}).$$

Since  $u^*(\cdot, t) \in C(\Omega^*)$ , we see that

$$u^*(\mu(s), t) = s \quad \text{for } 0 < s < u^*(0, t).$$

In [16] it is shown that  $u \in H^1(0, T; L^p(\Omega))$  implies that  $u^* \in H^1(0, T; L^p(\Omega^*))$ ,

$$\begin{aligned} \left\| \frac{\partial u^*}{\partial t}(\cdot, t) \right\|_{L^p(\Omega^*)} &\leq \left\| \frac{\partial u}{\partial t}(\cdot, t) \right\|_{L^p(\Omega)} \quad \text{a.a. } t, \\ \int_{\{u > s\}} \frac{\partial u}{\partial t} dx &= \frac{\partial k}{\partial t}(\mu(s), t) \quad \text{a.a. } (s, t), \end{aligned}$$

where

$$k(s, t) = \int_0^s u^*(\sigma, t) d\sigma \quad \text{for } s \in \overline{\Omega^*} \quad \text{and } t \in [0, T].$$

As for the regularity of  $k$ , we have

$$k \in L^\infty(Q_T^*) \cap H^1(0, T; W^{1,p}(\Omega^*)) \cap \bigcap_{\delta > 0} L^2(0, T; W^{2,p}(\delta, |\Omega|)),$$

where  $Q_T^* = \Omega^* \times (0, T)$ .

**Lemma 4.**  $k$  satisfies the following partial differential inequality and initial-boundary conditions

$$\begin{cases} \frac{\partial k}{\partial t} - d(s) \frac{\partial^2 k}{\partial s^2} - \alpha \chi k \frac{\partial k}{\partial s} \leq 0 \quad \text{a.e. in } Q_T^*, \\ k(0, t) = 0, \quad \frac{\partial k}{\partial s}(|\Omega|, t) = 0 \quad \text{for any } t \in [0, T], \\ k(s, 0) = \int_0^s u_0^*(\sigma) d\sigma \quad \text{for any } s \in \Omega^*, \end{cases}$$

where  $d(s) = N^2 \kappa_N^{2/N} s^{2(N-1)/N}$ .

*Proof.* For  $\tau \in (0, u^*(0, t))$  and  $h > 0$ , define the function  $T_{\tau, h}$  on  $(-\infty, \infty)$  by

$$T_{\tau, h}(s) = \begin{cases} 0 & \text{if } s \leq \tau, \\ s - \tau & \text{if } \tau < s \leq \tau + h, \\ h & \text{if } s > \tau + h. \end{cases}$$

$T_{\tau, h}(u(\cdot, t)) \in W_0^{1,p}(\Omega)$  since  $u(\cdot, t) \in W_0^{1,p}(\Omega)$  and  $T_{\tau, h}$  is Lipschitz continuous on  $(-\infty, \infty)$ . Multiply (1.1) by  $T_{\tau, h}(u)$  and integrate over  $\Omega$ . Integrating by parts gives

$$\int_{\Omega} \frac{\partial u}{\partial t} T_{\tau, h}(u) dx + \int_{\Omega} \nabla u \cdot \nabla T_{\tau, h}(u) dx - \chi \int_{\Omega} u \nabla v \cdot \nabla T_{\tau, h}(u) dx = 0.$$

From the definition of  $T_{\tau, h}$  and  $|\{u = \tau\}| = 0$  a.a.  $\tau > 0$  for each  $t \in (0, T)$  it follows that

$$\lim_{h \rightarrow 0} \frac{1}{h} \int_{\Omega} \frac{\partial u}{\partial t} T_{\tau, h}(u) dx = \int_{\{u > \tau\}} \frac{\partial u}{\partial t} dx = \frac{\partial k}{\partial t}(\mu(\tau), t).$$

We next see that

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{1}{h} \int_{\Omega} \nabla u \cdot \nabla T_{\tau, h}(u) dx &= \lim_{h \rightarrow 0} \frac{1}{h} \left( \int_{\{u > \tau\}} |\nabla u|^2 dx - \int_{\{u > \tau + h\}} |\nabla u|^2 dx \right) \\ &= -\frac{\partial}{\partial \tau} \int_{\{u > \tau\}} |\nabla u|^2 dx. \end{aligned}$$

Let us define the function  $\Phi_{\tau, h}$  on  $(-\infty, \infty)$  by

$$\Phi_{\tau, h}(s) = \int_0^s \sigma \frac{d}{d\sigma} T_{\tau, h}(\sigma) d\sigma = \begin{cases} 0 & \text{if } s \leq \tau, \\ \frac{1}{2}(s^2 - \tau^2) & \text{if } \tau < s \leq \tau + h, \\ h(\tau + \frac{h}{2}) & \text{if } s > \tau + h. \end{cases}$$

Multiplying (1.2) by  $\Phi_{\tau, h}(u(\cdot, t)) \in W_0^{1,p}(\Omega)$  and integrating over  $\Omega$  gives

$$J = \int_{\Omega} u \nabla v \cdot \nabla T_{\tau, h}(u) dx = \int_{\Omega} \nabla v \cdot \nabla \Phi_{\tau, h}(u) dx = \int_{\Omega} (\alpha u - \gamma v) \Phi_{\tau, h}(u) dx.$$

It follows from the definition of  $\Phi_{\tau, h}$  that

$$\begin{aligned} \frac{J}{h} &= \frac{1}{2h} \int_{\{\tau < u \leq \tau + h\}} (\alpha u - \gamma v)(u^2 - \tau^2) dx + \int_{\{u > \tau + h\}} (\alpha u - \gamma v) \left( \tau + \frac{h}{2} \right) dx \\ &\longrightarrow \tau \int_{\{u > \tau\}} (\alpha u - \gamma v) dx \quad \text{as } h \longrightarrow 0. \end{aligned}$$

By  $u^*(\mu(\tau), t) = \tau$  and

$$\int_{\{u > \tau\}} u dx = \int_0^{\mu(\tau)} u^*(\sigma, t) d\sigma,$$

we have

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{J}{h} &= u^*(\mu(\tau), t) \left\{ \alpha \int_0^{\mu(\tau)} u^*(\sigma, t) d\sigma - \gamma \int_{\{u > \tau\}} v dx \right\} \\ &= \frac{\partial k}{\partial s}(\mu(\tau), t) \left\{ \alpha k(\mu(\tau), t) - \gamma \int_{\{u > \tau\}} v dx \right\}. \end{aligned}$$

Hence,

$$\frac{\partial k}{\partial t}(\mu(\tau), t) - \frac{\partial}{\partial \tau} \int_{\{u > \tau\}} |\nabla u|^2 dx - \chi \frac{\partial k}{\partial s}(\mu(\tau), t) \left\{ \alpha k(\mu(\tau), t) - \gamma \int_{\{u > \tau\}} v dx \right\} = 0,$$

which together with  $u^* \geq 0$  and  $v \geq 0$  yields that

$$(3.1) \quad -\frac{\partial}{\partial \tau} \int_{\{u > \tau\}} |\nabla u|^2 dx \leq -\frac{\partial k}{\partial t}(\mu(\tau), t) + \alpha \chi k(\mu(\tau), t) \frac{\partial k}{\partial s}(\mu(\tau), t)$$

To estimate further we need the following inequality (see [8, 15, 20]):

$$N \kappa_N^{1/N} \mu(\tau)^{(N-1)/N} \leq (-\mu'(\tau))^{1/2} \left( -\frac{\partial}{\partial \tau} \int_{\{u > \tau\}} |\nabla u|^2 dx \right)^{1/2}.$$

From this inequality and (3.1) it follows that

$$N^2 \kappa_N^{2/N} \mu(\tau)^{2(N-1)/N} \leq -\mu'(\tau) \left\{ -\frac{\partial k}{\partial t}(\mu(\tau), t) + \alpha \chi k(\mu(\tau), t) \frac{\partial k}{\partial s}(\mu(\tau), t) \right\},$$

which implies that for almost all  $\tau \in (0, u^*(0, t))$ ,

$$(3.2) \quad 1 \leq N^{-2} \kappa_N^{-2/N} \mu(\tau)^{2(1-N)/N} (-\mu'(\tau)) \left\{ -\frac{\partial k}{\partial t}(\mu(\tau), t) + \alpha \chi k(\mu(\tau), t) \frac{\partial k}{\partial s}(\mu(\tau), t) \right\}.$$

The function  $G(s, t) = -\partial k / \partial t(s, t) + \alpha \chi k(s, t) \partial k / \partial s(s, t)$  is continuous on  $[0, |\Omega|]$  for fixed  $t$ . By using  $|\{u(\cdot, t) > 0\}| = |\Omega|$  and a similar way in Lemma 2 in [10], we see that  $G(s, t) \geq 0$  on  $[0, |\Omega|]$  for fixed  $t$ . Integrate (3.2) over  $(\tau_1, \tau_2) \subset [0, |\Omega|]$ . By a similar way in Lemma 2 in [10], we get

$$\tau_1 - \tau_2 \leq N^{-2} \kappa_N^{-2/N} \int_{\mu(\tau_1)}^{\mu(\tau_2)} s^{2(1-N)/N} \left\{ -\frac{\partial k}{\partial t}(s, t) + \alpha \chi k(s, t) \frac{\partial k}{\partial s}(s, t) \right\} ds,$$

and then, for almost all  $s$  in  $\Omega^*$

$$0 \leq -\frac{\partial^2 k}{\partial s^2}(s, t) = -\frac{\partial u^*}{\partial s}(s, t) \leq N^{-2} \kappa_N^{-2/N} s^{2(1-N)/N} \left\{ -\frac{\partial k}{\partial t}(s, t) + \alpha \chi k(s, t) \frac{\partial k}{\partial s}(s, t) \right\},$$

which implies the desired partial differential inequality.  $\square$

Let  $(U, V)$  be a solution of the symmetrized problem  $\text{SP}_D(\tilde{\Omega})$  on  $\tilde{Q}_T$ . We have seen in Sect. 2 that  $(U, V)$  is a classical solution and that  $U$  and  $V$  are non-negative and radially symmetric in  $x$ .

**Lemma 5.**  $U$  and  $V$  decrease along the radii. Hence,  $U = \tilde{U}$  and  $V = \tilde{V}$ .

*Proof.* We rewrite (1.5) and (1.6) in terms of  $r = |x|$  as

$$(3.3) \quad \begin{cases} \frac{\partial U}{\partial t} = r^{1-N} \frac{\partial}{\partial r} \left\{ r^{N-1} \left( \frac{\partial U}{\partial r} - \chi U \frac{\partial V}{\partial r} \right) \right\}, \\ 0 = r^{1-N} \frac{\partial}{\partial r} \left( r^{N-1} \frac{\partial V}{\partial r} \right) + \alpha U. \end{cases}$$

It is easy to get

$$r^{N-1} \frac{\partial V}{\partial r} = -\alpha \int_0^r U \rho^{N-1} d\rho,$$

from which together with  $U \geq 0$  it follows that  $\partial V / \partial r \leq 0$ . Hence,  $V$  decreases along the radii.

By (3.3),

$$\frac{\partial U}{\partial t} = \frac{\partial^2 U}{\partial r^2} + \frac{N-1}{r} \frac{\partial U}{\partial r} - \chi \left( \frac{\partial V}{\partial r} \frac{\partial U}{\partial r} - \alpha U^2 \right).$$

Differentiating this relation with respect to  $r$  and putting  $w = \partial U / \partial r$ , we get

$$\frac{\partial w}{\partial t} = \Delta w - \chi \nabla V \cdot \nabla w + C(x, t)w \quad \text{in } \tilde{Q}_T,$$

where

$$C(x, t) = -\frac{N-1}{|x|^2} - \chi \frac{\partial^2 V}{\partial r^2}(|x|, t) + 2\alpha \chi U.$$

We note that  $C(x, t)$  is bounded above on  $\tilde{Q}_T$  by  $U \in L^\infty(Q_T)$  and the second equation in (3.3). Hence, by  $w \leq 0$  on  $\partial \tilde{\Omega} \times (0, T)$  and  $w(x, 0) \leq 0$  on  $\Omega$ , the maximum principle yields that  $w \leq 0$  on  $\tilde{Q}_T$ .  $\square$

Define the function  $K$  on  $\overline{Q_T^*}$  by

$$(3.4) \quad K(s, t) = \int_0^s U^*(\sigma, t) d\sigma.$$

We then have the following lemma.

**Lemma 6.**  $K$  and  $V^*$  satisfy the following:

$$(i) \quad K \in L^\infty(Q_T^*) \cap H^1(0, T; W^{1,p}(\Omega^*)) \cap \bigcap_{\delta > 0} L^2(0, T; W^{2,p}(\delta, |\Omega|)),$$

$$(ii) \quad V^*(\cdot, t) \in C^1(\Omega^*) \quad \text{for } t > 0,$$

$$(iii) \quad d(s) \frac{\partial V^*}{\partial s} + \alpha K = 0 \quad \text{in } Q^*,$$

$$(iv) \quad \frac{\partial K}{\partial t} - d(s) \frac{\partial^2 K}{\partial s^2} - \alpha \chi K \frac{\partial K}{\partial s} = 0 \quad \text{in } Q^*,$$

$$(v) \quad K(s, 0) = k(s, 0) \quad \text{on } \Omega^* \quad \text{and } K(0, t) = 0, \quad \frac{\partial K}{\partial s}(|\Omega|, t) = 0 \quad \text{for any } t \in [0, T].$$

*Proof.* For  $\hat{\psi} \in C_0^\infty(\Omega^*)$  let us define

$$\psi(s) = \int_s^{|\Omega|} \hat{\psi}(\sigma) d\sigma \quad \text{and} \quad \varphi(x) = \psi(\kappa_N |x|^N).$$

Multiply (1.6) by  $\varphi \in C_0^1(\tilde{\Omega})$  and integrate over  $\tilde{\Omega}$ . Integrating by parts and using  $U^* = \partial K / \partial s$  gives

$$\begin{aligned} 0 &= \int_{\tilde{\Omega}} (\nabla V \cdot \nabla \varphi - \alpha U \varphi) dx = \int_{\Omega^*} \left( d(s) \frac{\partial V^*}{\partial s} \frac{d\psi}{ds} - \alpha U^* \psi \right) ds \\ &= - \int_{\Omega^*} \left( d(s) \frac{\partial V^*}{\partial s} + \alpha K \right) \hat{\psi} ds, \end{aligned}$$

which implies (iii). Next, multiply (1.5) by  $\varphi$  and integrate over  $\tilde{\Omega}$ . Using integration by parts, we obtain

$$\begin{aligned} 0 &= \int_{\tilde{\Omega}} \left\{ \frac{\partial U}{\partial t} \varphi + (\nabla U - \chi U \nabla V) \cdot \nabla \varphi \right\} dx \\ &= \int_{\Omega^*} \left\{ \frac{\partial U^*}{\partial t} \psi + d(s) \left( \frac{\partial U^*}{\partial s} - \chi U \frac{\partial V^*}{\partial s} \right) \frac{d\psi}{ds} \right\} ds \\ &= - \int_{\Omega^*} \left\{ -\frac{\partial K}{\partial t} + d(s) \left( \frac{\partial^2 K}{\partial s^2} - \chi \frac{\partial K}{\partial s} \frac{\partial V^*}{\partial s} \right) \right\} \hat{\psi} ds, \end{aligned}$$

from which together with (iii) we get (iv).  $\square$

We are now in a position to give the integral comparison.

**Theorem 2.** *The following inequalities hold:*

$$(i) \quad \int_0^s u^*(\sigma, t) d\sigma \leq \int_0^s U^*(\sigma, t) d\sigma \quad \text{for } (s, t) \in \overline{\Omega^*} \times [0, T].$$

$$(ii) \quad \|u(\cdot, t)\|_{L^r(\Omega)} \leq \|U(\cdot, t)\|_{L^r(\tilde{\Omega})} \quad \text{for } t \in [0, T] \quad \text{and } r \in [1, \infty].$$

*Proof.* (i) implies (ii) (see [4, 8]). From  $u, U \in L^\infty(Q_T)$  the condition (ii) in Proposition A1 follows. Hence, by applying Proposition A1, (i) is obtained.  $\square$

**Remark.** Under the homogeneous Dirichlet boundary condition on  $v$  in  $\mathbf{P}_D(\Omega)$ , we establish the mass comparison for  $v^*$  and  $V^*$

$$\int_0^s v^*(\sigma, t) d\sigma \leq \int_0^s V^*(\sigma, t) d\sigma$$

by using the inequality on  $u^*$  and  $U^*$  in Theorem 2 and the standard approach ( see for example, Theorem 1.26 and Remark 1.16 in [8], Corollary 1.4 in [15]). As a matter of fact, we can prove the stronger comparison  $v^* \leq V^*$ .

#### 4. Global existence and exponential decay

A function  $(a(x), b(x))$  on  $\bar{\Omega}$  is called a stationary solution to the problem  $\mathbf{P}_D(\Omega)$  if  $(a, b)$  satisfies the following

$$\begin{cases} a, b \in L^\infty(\Omega) \cap W^{2,2}(\Omega), \\ \nabla \cdot (\nabla a - \chi a \nabla b) = 0, \quad \Delta b - \gamma b + \alpha a = 0 \quad \text{in } \Omega, \\ a = 0, \quad \mathcal{B}b = 0 \quad \text{on } \partial\Omega. \end{cases}$$

**Proposition 1.** *There is no stationary solution to  $\mathbf{P}_D(\Omega)$  except  $(a, b) = (0, 0)$ .*

*Proof.* By the following relation

$$e^{xb} \nabla (ae^{-xb}) = \nabla a - \chi a \nabla b,$$

we get

$$(4.1) \quad \nabla \cdot \{e^{xb} \nabla (ae^{-xb})\} = \nabla \cdot (\nabla a - \chi a \nabla b) = 0.$$

Multiply (4.1) by  $ae^{-xb}$  and integrate over  $\Omega$ . Integrating by parts, we have

$$\int_{\Omega} e^{xb} |\nabla (ae^{-xb})|^2 dx = - \int_{\Omega} \nabla \cdot \{e^{xb} \nabla (ae^{-xb})\} ae^{-xb} dx = 0,$$

which implies that

$$\nabla (ae^{-xb}) = 0 \quad \text{on } \Omega.$$

Since  $a = 0$  on  $\partial\Omega$ , we get  $a \equiv 0$  on  $\Omega$ . The maximum principle for  $0 = \Delta b - \gamma b$  in  $\Omega$  with  $\mathcal{B}b = 0$  on  $\partial\Omega$  gives  $b \equiv 0$  on  $\Omega$ .  $\square$

Let  $(u, v)$  be a non-negative solution of  $\mathbf{P}_D(\Omega)$ . We will give an application of Theorem 2, which gives the global existence of the solution to  $\mathbf{P}_D(\Omega)$  and the exponential decay of  $(u, v)$  to  $(0, 0)$  as  $t \rightarrow \infty$  through the estimation of the solution  $(U, V)$  to the symmetrized problem  $\mathbf{SP}_D(\tilde{\Omega})$ . We denote a maximal existence time of  $(U, V)$  by  $T_{max}^*$ . For  $U$ , let  $K(s, t)$  be the one defined in (3.4).

**Lemma 7.** *If  $K(s, t) \leq \text{Const.} \sqrt{d(s)}$  on  $\Omega^* \times (0, T_{max}^*)$ , then*

$$\|V(\cdot, t)\|_{L^\infty(\tilde{\Omega})} \leq \text{Const.}, \quad \|\nabla V(\cdot, t)\|_{L^\infty(\tilde{\Omega})} \leq \text{Const.} \quad \text{on } (0, T_{max}^*).$$

*Proof.* By Lemma 6,

$$0 = d(s) \frac{\partial V^*}{\partial s} + \alpha K \quad \text{in } \Omega^* \times (0, T_{max}^*).$$

Hence,

$$\frac{\partial V}{\partial r} = \sqrt{d(s)} \frac{\partial V^*}{\partial s} = - \frac{\alpha K}{\sqrt{d(s)}} \quad (r = |x|, s = \kappa_N r^N),$$

which implies

$$\|\nabla V(\cdot, t)\|_{L^\infty(\tilde{\Omega})} \leq \text{Const.} \quad \text{on } (0, T_{max}^*).$$

By  $V(|\Omega|, t) = 0$  and the estimate of  $\nabla V$ , we get the desired estimate about  $V$ .  $\square$

**Lemma 8.** *Assume that*

$$\|\nabla V(\cdot, t)\|_{L^\infty(\tilde{\Omega})} \leq \text{Const.} \quad \text{on } (0, T_{max}^*).$$

*If there exists a constant  $\lambda \geq 0$  such that*

$$\|U(\cdot, t)\|_{L^1(\tilde{\Omega})} \leq \text{Const.} e^{-\lambda t} \quad \text{for } t \in (0, T_{max}^*),$$

*then  $T_{max}^* = \infty$  and*

$$\|U(\cdot, t)\|_{L^\infty(\tilde{\Omega})} \leq \text{Const.} e^{-\lambda t} \quad \text{for } t > 0.$$

*Proof.* Define the function  $f$  by

$$f(x, t) = e^{\lambda t} U(x, t) \quad \text{on } \tilde{\Omega} \times [0, T_{max}^*),$$

which satisfies

$$\|f(\cdot, t)\|_{L^1(\tilde{\Omega})} \leq \text{Const.} \quad \text{on } [0, T_{max}^*).$$

We see that  $f$  satisfies

- (i)  $f \in L^\infty(\tilde{Q}_T) \cap L^2(0, T; W_0^{1,2}(\tilde{\Omega})) \cap H^1(0, T; L^2(\tilde{\Omega}))$  for any  $T \in (0, T_{max}^*)$ ,
- (ii) for any  $\varphi \in W_0^{1,2}(\tilde{\Omega})$  and  $t \in (0, T_{max}^*)$ ,

$$\int_{\tilde{\Omega}} \left\{ \frac{\partial f}{\partial t} \varphi + (\nabla f - \chi f \nabla V) \cdot \nabla \varphi - \lambda f \varphi \right\} dx = 0,$$

- (iii)  $f(\cdot, 0) = \tilde{u}_0 \in L^\infty(\tilde{\Omega})$ .

By Proposition A2, we get

$$\|f(\cdot, t)\|_{L^\infty(\tilde{\Omega})} \leq \text{Const.} \quad \text{on } (0, T_{max}^*),$$

which implies  $T_{max}^* = \infty$  and the desired inequality.  $\square$

**Proposition 2.** *Under each of (C1)–(C3),  $T_{max}^* = \infty$  and there exists a positive constant  $\lambda$  such that*

$$(4.2) \quad \|U(\cdot, t)\|_{L^\infty(\tilde{\Omega})} \leq \text{Const.} e^{-\lambda t} \quad \text{for } t > 0.$$

*Proof.* Let us consider under (C1). Define the function  $Z$  by

$$Z(s, t) = e^{-\lambda t} w(s), \quad w(s) = p \frac{e^{\alpha \chi p s / 2} - 1}{e^{\alpha \chi p s / 2} + 1},$$



where  $\lambda$  and  $p$  are positive constants determined below. Take  $p$  so large that

$$K(s, 0) \leq w(s) \quad \text{on } \overline{\Omega^*}.$$

Choosing  $\lambda$  such that

$$0 < \lambda \leq \alpha\chi w'(|\Omega|),$$

we get

$$\begin{aligned} \frac{\partial Z}{\partial t} - d(s) \frac{\partial^2 Z}{\partial s^2} - \alpha\chi Z \frac{\partial Z}{\partial s} &= e^{-\lambda t} \{-\lambda w + \alpha\chi (2 - e^{-\lambda t}) ww'\} \\ &> e^{-\lambda t} w(-\lambda + \alpha\chi w'(|\Omega|)) \geq 0. \end{aligned}$$

Here we have used that  $w'$  is decreasing. Noting that  $Z(0, t) = 0$  and  $\partial Z/\partial s(|\Omega|, t) > 0$ , by Proposition A1 we get

$$K(s, t) \leq Z(s, t) \quad \text{on } \Omega^* \times [0, T_{max}^*],$$

which implies that

$$K(s, t) \leq \text{Const.} \sqrt{d(s)}. \quad \text{on } \Omega^* \times [0, T_{max}^*]$$

and

$$\|U(\cdot, t)\|_{L^1(\tilde{\Omega})} = K(|\Omega|, t) \leq \text{Const.} e^{-\lambda t} \quad \text{for } t \in (0, T_{max}^*).$$

Therefore, by Lemmas 7 and 8, we have  $T_{max}^* = \infty$  and (4.2).

Under (C2), define the function  $Z$  by

$$Z(s, t) = e^{-\lambda t} \frac{pqs}{1+qs} \quad (s \in \overline{\Omega^*}, t \geq 0).$$

Choose  $p$  satisfying

$$K(|\Omega|, 0) < p \quad \text{and} \quad \alpha\chi p < 8\pi.$$

Take  $q$  so large that

$$K(s, 0) \leq \frac{pqs}{1+qs} = Z(s, 0) \quad \text{on } \overline{\Omega^*}.$$

We take  $\lambda$  satisfying

$$0 < \lambda \leq \frac{q}{(1+q|\Omega|)^2} (8\pi - \alpha\chi p).$$

We then get

$$\begin{aligned} \frac{\partial Z}{\partial t} - d(s) \frac{\partial^2 Z}{\partial s^2} - \alpha\chi Z \frac{\partial Z}{\partial s} &= \frac{pqs}{1+qs} \left\{ -\lambda + 8\pi \frac{q}{(1+qs)^2} - e^{-\lambda t} \alpha\chi p \frac{q}{(1+qs)^2} \right\} \\ &\geq \frac{pqs}{1+qs} \left\{ -\lambda + \frac{q}{(1+qs)^2} (8\pi - \alpha\chi p) \right\} \geq 0. \end{aligned}$$

Hence,  $Z$  satisfies

$$\begin{cases} \frac{\partial Z}{\partial t} - d(s) \frac{\partial^2 Z}{\partial s^2} - \alpha\chi Z \frac{\partial Z}{\partial s} \geq 0 & \text{in } \Omega^* \times (0, \infty), \\ Z(0, t) = 0, \quad \frac{\partial Z}{\partial s}(|\Omega|, t) \geq 0 & \text{on } (0, \infty), \\ Z(s, 0) \geq K(s, 0) & \text{on } \overline{\Omega^*}. \end{cases}$$

By Proposition A1,

$$K(s, t) \leq Z(s, t) \quad \text{on } \overline{\Omega^*} \times [0, T_{max}^*],$$

which implies (4.2).

Under (C3) let us choose  $\beta$  such that

$$\beta > \alpha\chi \quad \text{and} \quad \beta \|u_0\|_{L^N(\Omega)} \leq N \kappa_N^{\frac{2}{N}} |\Omega|^{-\frac{1}{N}}.$$

Define the function  $Z$  by

$$Z(s, t) = e^{-\lambda t} w(s), \quad w(s) = qs^{1-\frac{1}{N}}, \quad q = \frac{N}{\beta} \kappa_N^{\frac{2}{N}} |\Omega|^{-\frac{1}{N}},$$

where  $\lambda$  is a constant satisfying

$$0 < \lambda \leq (\beta - \alpha\chi) w'(|\Omega|).$$

Then,

$$\frac{\partial Z}{\partial t} - d(s) \frac{\partial^2 Z}{\partial s^2} - \alpha\chi Z \frac{\partial Z}{\partial s} \geq e^{-\lambda t} w \{-\lambda + (\beta - \alpha\chi) w'(|\Omega|)\} \geq 0.$$

Using Hölder's inequality and  $\|u_0^*\|_{L^N(\Omega^*)} = \|u_0\|_{L^N(\Omega)}$ , we have

$$K(s, 0) = \int_0^s u_0^* d\sigma \leq Z(s, 0).$$

Noting that  $Z(0, t) = 0$  and  $\partial Z/\partial s(|\Omega|, t) > 0$ , by Proposition A1 we get  $K(s, t) \leq Z(s, t)$ , which implies (4.2).  $\square$

From Theorem 2 and Proposition 2 the exponential decay of the non-negative solution  $(u, v)$  of the problem  $\mathbf{P}_D(\Omega)$  is obtained.

**Theorem 3.** *Under each of (C1)–(C3),  $T_{max} = \infty$  and there exists a positive constant  $\lambda$  such that*

$$\|u(\cdot, t)\|_{L^\infty(\Omega)} + \|v(\cdot, t)\|_{L^\infty(\Omega)} \leq \text{Const.} e^{-\lambda t} \quad \text{for } t > 0.$$

*Proof.* By Theorem 2 and Proposition 2,

$$(4.3) \quad \|u(\cdot, t)\|_{L^\infty(\Omega)} \leq \|U(\cdot, t)\|_{L^\infty(\Omega)} \leq \text{Const.} e^{-\lambda t} \quad \text{for } 0 < t < T_{max}.$$

Hence,  $T_{max} = \infty$  by Theorem 1, and

$$\|u(\cdot, t)\|_{L^\infty(\Omega)} \leq \text{Const.} e^{-\lambda t} \quad \text{for } t > 0.$$

Since the function  $v(\cdot, t)$  satisfies

$$\begin{cases} v(\cdot, t) \in L^\infty(\Omega) \cap W^{2,p}(\Omega), \\ (\Delta - \gamma)v(\cdot, t) = -\alpha u(\cdot, t) \quad \text{in } \Omega, \\ \mathcal{B}v = 0 \quad \text{on } \partial\Omega, \end{cases}$$

$v(\cdot, t)$  is estimated as

$$\|v(\cdot, t)\|_{L^\infty(\Omega)} \leq \text{Const.} \|u(\cdot, t)\|_{L^\infty(\Omega)},$$

which together with (4.3) establishes the conclusion of the theorem.

## Appendix

In what follows,  $C_1(t)$  is a generic positive function on  $(0, T)$  belonging to  $L^2(0, T)$ .

**Proposition A1.** *Let  $f$  and  $g$  be functions on  $\overline{Q_T^*}$  satisfying the following:*

$$(i) \ f, g \in L^\infty(Q_T^*) \cap H^1(0, T; L^2(\Omega^*)) \cap \bigcap_{s>0} L^2(0, T; W^{2,2}(\delta, |\Omega|)).$$

$$(ii) \ \left| \frac{\partial f}{\partial s}(s, t) \right| \leq C_1(t) \quad \text{and} \quad \left| \frac{\partial g}{\partial s}(s, t) \right| \leq C_1(t)s^{-\ell} \quad \text{on } Q_T^* \cap \{0 < s < 1\},$$

where  $\ell$  is a constant satisfying  $0 \leq \ell < 1$ .

$$(iii) \ \frac{\partial f}{\partial t} - d(s) \frac{\partial^2 f}{\partial s^2} - \alpha \chi f \frac{\partial f}{\partial s} \leq \frac{\partial g}{\partial t} - d(s) \frac{\partial^2 g}{\partial s^2} - \alpha \chi g \frac{\partial g}{\partial s} \quad \text{a.e. in } Q_T^*,$$

where  $d(s) = N^2 \kappa_N^{2/N} s^{2(N-1)/N}$ .

$$(iv) \ 0 = f(0, t) \leq g(0, t) \quad \text{and} \quad \frac{\partial f}{\partial s}(|\Omega|, t) \leq \frac{\partial g}{\partial s}(|\Omega|, t) \quad \text{for any } t \in [0, T].$$

$$(v) \ f(s, 0) \leq g(s, 0) \quad \text{on } \Omega^* \quad \text{and} \quad g(s, t) \geq 0 \quad \text{on } Q_T^*.$$

Then

$$f \leq g \quad \text{on } Q_T^*.$$

*Proof.* Put  $w = f - g$ , which satisfies

$$(A.1) \quad \begin{cases} \frac{\partial w}{\partial t} - d(s) \frac{\partial^2 w}{\partial s^2} - \alpha \chi \left( f \frac{\partial f}{\partial s} - g \frac{\partial g}{\partial s} \right) \leq 0 \quad \text{a.e. in } Q_T^*, \\ w(0, t) \leq 0, \quad \frac{\partial w}{\partial s}(|\Omega|, t) \leq 0 \quad \text{for any } t \in [0, T], \\ w(s, 0) \leq 0 \quad \text{for any } s \in [0, |\Omega|]. \end{cases}$$

Multiplying the differential inequality in (A.1) by  $s^{2(1-N)/N} w_+$ , where  $w_+ = \max\{w, 0\}$ , we get

$$s^{2(1-N)/N} \frac{\partial w}{\partial t} w_+ \leq N^2 \kappa_N^{2/N} \frac{\partial^2 w}{\partial s^2} w_+ + \alpha \chi s^{2(1-N)/N} \left( f \frac{\partial f}{\partial s} - g \frac{\partial g}{\partial s} \right) w_+ \quad \text{a.e. in } Q_T^*.$$

By  $g \geq 0$ ,  $f(0, t) = 0$  and (ii), we have

$$(A.2) \quad w_+(s, t) \leq f(s, t) \leq C_1(t)s \quad \text{on } \{s \in \Omega^*; w_+(s, t) > 0\} \cap \{0 < s < 1\}.$$

From (A.2) it follows that  $s^{2(1-N)/N} (w_+)^2$  belongs to  $L^1(\Omega^*)$ . Let us take  $\delta$  satisfying  $0 < \delta < |\Omega|$ . Using the integration by parts and  $\partial w / \partial s(|\Omega|, t) \leq 0$  yields that

$$\int_\delta^{|\Omega|} \frac{\partial^2 w}{\partial s^2} w_+ ds \leq -\frac{\partial w}{\partial s}(\delta, t) w_+(\delta, t) - \int_\delta^{|\Omega|} \left( \frac{\partial w_+}{\partial s} \right)^2 ds.$$

We next have

$$\begin{aligned} & \alpha \chi \int_\delta^{|\Omega|} s^{2(1-N)/N} \left( f \frac{\partial f}{\partial s} - g \frac{\partial g}{\partial s} \right) w_+ ds \\ &= \alpha \chi \int_\delta^{|\Omega|} s^{2(1-N)/N} (w_+)^2 \frac{\partial f}{\partial s} ds + \alpha \chi \int_\delta^{|\Omega|} s^{2(1-N)/N} w_+ \frac{\partial w}{\partial s} g ds \\ &\leq C_1(t) \int_{\Omega^*} s^{2(1-N)/N} (w_+)^2 ds + \alpha \chi \int_\delta^{|\Omega|} s^{2(1-N)/N} w_+ \left| \frac{\partial w_+}{\partial s} \right| f ds. \end{aligned}$$

Using (A.2) and Hölder's inequality, we obtain

$$\begin{aligned} & \alpha \chi \int_\delta^{|\Omega|} s^{2(1-N)/N} w_+ \left| \frac{\partial w_+}{\partial s} \right| f ds \leq C_1(t) \int_\delta^{|\Omega|} s^{(1-N)/N} w_+ \left| \frac{\partial w_+}{\partial s} \right| ds \\ &\leq \frac{1}{2} N^2 \kappa_N^{2/N} \int_\delta^{|\Omega|} \left( \frac{\partial w_+}{\partial s} \right)^2 ds + \{C_1(t)\}^2 \int_{\Omega^*} s^{2(1-N)/N} (w_+)^2 ds. \end{aligned}$$

Hence,

$$\begin{aligned} & \frac{d}{dt} \int_\delta^{|\Omega|} s^{2(1-N)/N} w_+^2 ds + N^2 \kappa_N^{2/N} \int_\delta^{|\Omega|} \left( \frac{\partial w_+}{\partial s} \right)^2 ds \\ &\leq \{C_1(t)\}^2 \int_{\Omega^*} s^{2(1-N)/N} w_+^2 ds + \text{Const.} \left| \frac{\partial w}{\partial s}(\delta, t) \right| w_+(\delta, t) \quad \text{for } t \in (0, T), \end{aligned}$$

from which together with  $w_+(s, 0) = 0$  on  $\Omega^*$  it follows that for  $t \in (0, T)$ ,

$$\int_\delta^{|\Omega|} s^{2(1-N)/N} w_+(s, t)^2 ds$$

$$\leq \int_0^t \{C_1(\tau)\}^2 \left( \int_{\Omega^*} s^{2(1-N)/N} w_+^2 ds \right) d\tau + \text{Const.} \int_0^t \left| \frac{\partial w}{\partial s}(\delta, \tau) \right| w_+(\delta, \tau) d\tau.$$

Note that  $|(\partial w/\partial s)(\delta, t)|w_+(\delta, t) \leq \{C_1(t)\}^2 \delta^{1-t}$ . Letting  $\delta \rightarrow 0$ , we get

$$\int_{\Omega^*} s^{2(1-N)/N} w_+(s, t)^2 ds \leq \int_0^t \{C_1(\tau)\}^2 \left( \int_{\Omega^*} s^{2(1-N)/N} w_+^2 ds \right) d\tau \quad \text{for } t \in (0, T).$$

By Gronwall's inequality,

$$\int_{\Omega^*} s^{2(1-N)/N} w_+(s, t)^2 ds = 0 \quad \text{for } t \in (0, T],$$

which implies  $w_+ = 0$  in  $\overline{Q_T^*}$ . Hence,  $f \leq g$ .  $\square$

The following proposition is obtained by using Moser's technique (see Alikakos[1]).

**Proposition A2.** *Assume that there exists a positive constant  $C$  independent of  $T$  such that*

$$|a(x, t)| \leq C, \quad b(x, t) \leq C \quad \text{on } Q_T.$$

Let  $w$  be a non-negative function on  $Q_T$  such that

$$(i) \quad w \in L^\infty(Q_T) \cap L^2(0, T; W_0^{1,2}(\Omega)) \cap H^1(0, T; L^2(\Omega)),$$

$$(ii) \quad \text{for almost all } t \in (0, T) \text{ and all } \varphi \in W_0^{1,2}(\Omega) \text{ with } \varphi \geq 0,$$

$$\int_{\Omega} \left\{ \frac{\partial w}{\partial t} \varphi + (\nabla w + w a) \cdot \nabla \varphi - b w \varphi \right\} dx \leq 0.$$

Then there exists a positive constant  $C$  independent of  $T$  such that

$$\sup_{0 \leq t \leq T} \|w(\cdot, t)\|_{L^\infty(\Omega)} \leq C \max\{1, \|w(\cdot, 0)\|_{L^\infty(\Omega)}, \sup_{0 \leq t \leq T} \|w(\cdot, t)\|_{L^1(\Omega)}\}.$$

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