

Behaviour on the boundary of solutions of parabolic equations with nonlinear boundary conditions: the parabolic Signorini problem.

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Let Ω be an open regular set of \mathbb{R}^N and consider the following nonlinear parabolic boundary value problem

$$(1) \begin{cases} u_t - \Delta u = f(t,x) & \text{in } \Omega \times (0,\infty) = Q \\ u(0,\cdot) = u_0 & \text{on } \Omega \\ \frac{\partial u}{\partial n} + b(u) = g(t,x) & \text{on } \partial\Omega \times (0,\infty) = \Sigma, \end{cases}$$

where n is the unit outward normal to $\partial\Omega$ and b is a continuous non-decreasing function such that $b(0) = 0$. Many different results are well-known on the existence and uniqueness of solutions u under several kind of regularity assumptions on f , u_0 and g (see, for instance, Friedman [8] Amann [2] and Alikakos [1]). It is also well-known that if $f \geq 0$, $u_0 \geq 0$ and $g \geq 0$ then $u \geq 0$ in \bar{Q} . In fact, by the strong maximum principle, if u is nonnegative and $u(t,\cdot) \not\equiv 0$ for every $t > 0$, then $u > 0$ on Q . A natural question arise: For which functions b , the behaviour of u near Σ becomes pathological, in the sense that $u(t,\cdot)|_{\Sigma}$ vanishes on some subregion of Σ ? A first answer is easy because, again, by the maximum principle if $u(t,x) = 0$ on $\Gamma_0 \times (t_0, \infty)$ then we arrive to the contradiction $0 > \frac{\partial u}{\partial n}(t,x) = g(t,x) - b(0) \geq 0$, on $\Gamma_0 \times (t_0, \infty)$. So, this behaviour is excluded for any nondecreasing continuous function b such that $b(0) = 0$ and for which $u(t,\cdot) \not\equiv 0$ for any $t > 0$.

The situation changes strongly if we take b in the class of the multivalued maximal monotone graphs of \mathbb{R}^2 (that we shall denote by β). That general formulation is of interest in the applications (see Duvaut-Lions [7]) and now the problem is

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$$P(f, u_0, g) \begin{cases} u_t - \Delta u = f(t, x) & \text{in } Q \\ u(0, \cdot) = u_0 & \text{on } \Omega \\ -\frac{\partial u}{\partial n} + g(t, x) \in \beta(u) & \text{on } \Sigma. \end{cases}$$

In fact, we shall pay our attention on the particular case of β given by

$$(2) \quad \beta(r) = 0 \quad \text{if } r > 0, \quad \beta(0) = (-\infty, 0] \quad \text{and} \quad \beta(r) = \emptyset \quad (\text{the empty set}).$$

That problem is associated to the name of Signorini parabolic problem. Note that in this case the boundary conditions are of "unilateral type"

$$(3) \quad u \geq 0, \quad -\frac{\partial u}{\partial n} + g \leq 0 \quad \text{and} \quad u(-\frac{\partial u}{\partial n} + g) = 0, \quad \text{on } \Sigma,$$

and that the coincidence set, defined by $\Sigma_0 = \{(t, x) \in \Sigma : u(t, x) = 0\}$, plays an important role in the understanding of the problem. Our question now is the study of the assumptions on f , u_0 and g that allow the formation of the coincidence set Σ_0 . A first homogenization Lemma show us that we shall may assume, without loss of generality, that $f \equiv 0$ and $u_0 \equiv 0$.

Lemma. *Let u solution of $P(f, u_0, g)$ and v satisfying $v_t - \Delta v = f$ in Q , $v(0, \cdot) = u_0$ on Ω , and $v = 0$ in Σ . Then the function $U = u - v$ satisfies $P(0, 0, \tilde{g})$, where*

$$(4) \quad \tilde{g} \equiv g - \frac{\partial U}{\partial n}.$$

After this trivial remark, it seems natural that the existence or non-existence of the coincidence set Σ_0 will depends on the behaviour of this function \tilde{g} . We start with a necessary condition:

Theorem 1. *Let u be a (weak) solution of $P(f, u_0, g)$ for β given by (2). Assume that $u(t, \xi) = 0$ a.e. on $\Sigma_0 = (0, \infty) \times \Gamma_0$, where Γ_0 is a "smooth" part of $\partial\Omega$. Then necessarily $\tilde{g}(t, \xi) \leq 0$ a.e. on Σ_0 .*

Idea of the proof. Let $T > 0$ fixed. We first note that

$$(5) \quad -\int_{\Omega} u_0(x)v(0, x)dx + \int_0^T \int_{\partial\Omega} u \frac{\partial u}{\partial n} d\xi dt \geq \int_0^T \int_{\Omega} f v dx dt + \int_0^T \int_{\partial\Omega} g v d\xi dt$$

for any $v \in W^{1,2}(0,T;H^1(\Omega))$ such that $v_t + \Delta v = 0$ in $Q_T = (0,T) \times \Omega$, $v \geq -u$ on $\partial\Omega \times (0,T)$ and $v(T,x) = 0$ on Ω . Indeed, by regularizing the data f, u_0 and g , we may assume that u is a strong solution i.e. such that $u_t \in L^2$ and satisfies

$$\int_{Q_T} u_t(w-u) dxdt + \int_{Q_T} \nabla u \cdot \nabla(w-u) dxdt \geq \int_{Q_T} f(w-u) dxdt + \int_0^T \int_{\partial\Omega} g(w-u) d\xi dt$$

for every $w \in L^2(0,T;H^1(\Omega))$ with $w \geq 0$ in $\partial\Omega \times (0,T)$. Taking $w = v + u$ we obtain (5). But from the Lemma we may assume $f \equiv 0$, $u_0 \equiv 0$ and $g = \tilde{g}$ without loss of generality (note that $U = u$ on $\partial\Omega \times (0,\infty)$). Then we have that

$$\int_0^T \int_{\partial\Omega} u \frac{\partial v}{\partial n} d\xi dt \geq \int_0^T \int_{\partial\Omega} \tilde{g} v d\xi dt$$

for any v satisfying $v_t + \Delta v = 0$ in Q_T , $v \geq -u$ on Σ and $v(T,x) = 0$ on Ω . In particular, if we take $v(t,\xi) = \sigma(t,\xi)$ on Σ with $\sigma \geq 0$ arbitrary such that $\sigma(t,\xi) = 0$ on $\Sigma - \Sigma_0$, by the strong maximum principle we have that $\frac{\partial v}{\partial n} < 0$ on $\Sigma - \Sigma_0$ and so

$$\int_0^T \int_{\Gamma_0} \tilde{g}(t,\xi) \sigma(t,\xi) d\xi dt \leq 0$$

which gives the conclusion. #

As in the elliptic case (see Diaz-Jimenez [5]) the condition $\tilde{g}(t,\xi) \leq 0$ on a part of Σ is not enough for the formation of the coincidence set. Nevertheless, such a condition is almost sufficient as the following Theorem shows

Theorem 2. Assume, for simplicity, Ω be convex and let f, u_0 and g such that there exists $\epsilon > 0$ such that

$$\tilde{g}(t,\xi) < -\epsilon \quad \text{on a given part } \Gamma_\epsilon \text{ of } \partial\Omega \text{ and for any } t > 0.$$

Then there exists $R = R(\epsilon) > 0$ such that

$$\Sigma_0 \supset \{(t, \xi) \in [0, \infty) \times \Gamma_\varepsilon : d(\xi, \partial\Omega - \Gamma_\varepsilon) \geq R\}.$$

i.e. u vanishes, at least, on the part of the boundary Σ given by the right hand side set of the above expression.

A stronger result is possible: the coincidence set may occur only after a finite time. More precisely we have

Theorem 3. Assume Ω convex and let g and f such that there exists $\varepsilon > 0$, $\Gamma_\varepsilon \subset \partial\Omega$ and $t_\varepsilon > 0$ such that

$$g(t, \xi) - \frac{\partial F}{\partial n}(t, \xi) < -\varepsilon \text{ on } [t_\varepsilon, \infty) \times \Gamma_\varepsilon,$$

where $F(t, x)$ satisfies $F_t - \Delta F = f$ in Q_T , $F \equiv 0$ on $\partial\Omega \times (0, \infty)$ and $F(0, \cdot) = 0$ on Ω . Then, for any given initial data u_0 , the solution u of $P(f, u_0, g)$ satisfies that there exist a finite time $T_0 \geq t_\varepsilon$ such that

$$\Sigma_0 \supset \{(t, \xi) \in [T_0, \infty) \times \Gamma_\varepsilon : d(\xi, \partial\Omega - \Gamma_\varepsilon) \geq R\}$$

for some $R = R(\varepsilon)$. In particular if $\Gamma_\varepsilon = \partial\Omega$ then $u \equiv 0$ on $(T_0, \infty) \times \partial\Omega$ and u becomes the solution of the homogeneous Dirichlet problem after the time T_0 .

The proof of the above results is obtained through the construction of suitable local-supersolutions inspired in the elliptic case (Diaz-Jimenez [5]). For details, see Diaz-Jimenez [6] where the constants $R(\varepsilon)$ and T_0 are estimated.

We shall end this communication by giving an application of the above theorems to the study of the sign of the trace $u(t, \cdot)|_\Sigma$ of solutions of the initial problem (1) when f, g and u_0 don't have constant sign on their respective domains. So, assume, for instance, that $f \equiv 0$, $u_0 \equiv 0$ but $g(t, \xi)$ changes of sign on Σ . Even for the linear problem, $b(u) = u$, or $b(u) \equiv 0$ it is not an easy task to find regions of Σ where u is nonpositive (or nonnegative) when only the region of Σ where g is nonpositive (or nonnegative) is known. Nevertheless, by a variant of the comparison principle is not difficult to show that $u_\beta \leq u_\alpha$ (see e.g.

Brezis [4]), where u_b represents the solution of (1) and u_β satisfies $P(0,0,g)$ for β given by (2). In consequence, from Theorem 2 we deduce that if there exists $\varepsilon > 0$ such that $g(t,x) < -\varepsilon$ on a part Γ_ε of $\partial\Omega$ and any $t > 0$, then the trace $u_b(t,\cdot)$ on $\partial\Omega$ is such that $u_b(t,\cdot) < 0$ at least on the set $\{(t,\xi) \in [0,\infty) \times \Gamma_\varepsilon : d(\xi,\partial\Omega \setminus \Gamma_\varepsilon) \geq R\}$ for some $R = R(\varepsilon)$. The study of the regions of Σ where $u_b(t,\cdot)$ is nonnegative may be similarly estimated by studying previously the problem $P(f,u_0,g)$ for β given by $\tilde{\beta}(r) = -\beta(-r)$ with β defined in (2).

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