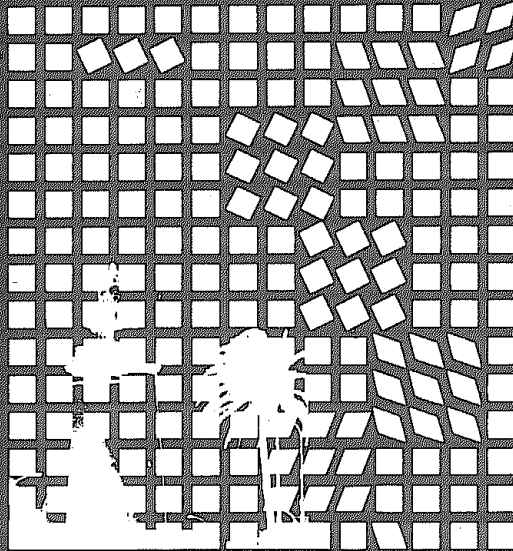


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MATHEMATICAL ANALYSIS OF THE CONVERSION OF A POROUS SOLID BY A DISTRIBUTED GAS REACTION

by

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1. Introduction. In this communication we present some of the results of a forthcoming article by the authors [11]. We consider the conversion (or combustion) of a porous solid, known as the *pellet*, as it reacts with a gas diffusing through its pores. Problems of this nature are of current interest in Chemical Engineering and Metallurgy. ([13],[21]). We assume that the reaction (which involves only one species of gas and one of the solid) is simple, irreversible and isothermal.

The gas, whose concentration is $v(x,t)$ is replenished from the ambient region. The porous solid occupies the domain Ω (an open regular and bounded set of \mathbb{R}^n with $n=3$ or $n=2$) and its concentration is $u(x,t)$. Here t denotes the time and x a macroscopic position vector. The reaction is taken to be of the form

$$R(u,v)=f(u)g(v)$$

where f and g are real continuous monotone nondecreasing functions such that $f(0)=g(0)=0$. After nondimensionalization and under some suitable simplifications mass balances yield (see e.g.[13],[21])

$$P_\varepsilon \begin{cases} u_t & = -f(u)g(v) & \text{in } \Omega \times (0,T) \equiv Q_T \\ \varepsilon v_t - \Delta v & = -\lambda f(u)g(v) & \text{in } Q_T \\ \alpha \frac{\partial v}{\partial n} & = 1-v & \text{on } \partial \Omega \times (0,T) \\ u(x,0) & = u_0(x) & \text{on } \Omega \\ v(x,0) & = v_0(x) & \text{on } \Omega \end{cases}$$

Here ε is the porosity (usually of the order 10^{-1} or 10^{-2}) and λ is the Thiele modulus ($1 \leq \lambda \leq 10^2$). The parameter α is assumed to be

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nonnegative ($\alpha=0$ corresponds to Dirichlet conditions). Some specially important choice of f and g are

$$f(u)=u^m, \quad g(v)=v^q, \quad m, q > 0, \quad (1)$$

where the case $m=2/3$ corresponds to the *Sohn-Szekely grain-pellet model* ([21]). For obvious reasons we assume $u_0 \geq 0$ and $v_0 \geq 0$ on Ω which, by the maximum principle, implies $u(x,t) \geq 0$ and $v(x,t) \geq 0$ on $\overline{\Omega} \times [0, T]$.

In section 2 we shall collect some results on the existence and uniqueness of solutions. Section 3 will be devoted to the "pseudo-steady-state problem" ($\varepsilon=0$) and, finally, in Section 4 we shall consider the solid conversion and gas penetration phenomena.

2. Existence, continuous dependence and uniqueness.

Given $(u_0, v_0) \in L^\infty(\Omega) \times L^\infty(\Omega)$ satisfying

$$0 \leq u_0(x) \leq 1, \quad 0 \leq v_0(x) \leq 1, \quad \text{a.e. } x \in \Omega, \quad (2)$$

the existence of a weak solution

$$(u, v) \in \left[C([0, T]; L^\infty(\Omega)) \cap W^{1,1}(0, T; L^2(\Omega)) \right] \times H^1(0, T; L^\infty(\Omega))$$

and such that

$$0 \leq u(x, t) \leq 1, \quad 0 \leq v(x, t) \leq 1, \quad \text{a.e. } (x, t) \in \Omega \quad (3)$$

can be proved in several different ways: monotone iterations [11] (see also [15] and [14]) and compactness arguments [12]. It is not difficult to show that if, for instance, f and g are Holder continuous then (u, v) is a classical solution in Q . Nevertheless there are particular examples showing that $u \notin C_t^2$ and $v \notin C_x^3$.

The following result gives a continuous dependence leading, in particular, to the uniqueness of solutions (that improves the previous result of [15] related to the case when f and g are Lipschitz continuous).

Theorem 1. *Let (u, v) and (u^*, v^*) be any solutions corresponding to the initial data (u_0, v_0) , (u_0^*, v_0^*) respectively. Then for any $t \in [0, T]$ we have*

$$\begin{aligned} & \varepsilon \int_{\Omega} |v(x, t) - v^*(x, t)| dx + \lambda \int_{\Omega} |u(x, t) - u^*(x, t)| dx + \\ & \frac{1}{\alpha} \int_0^t \int_{\partial\Omega} |v(\sigma, \tau) - v^*(\sigma, \tau)| d\tau d\sigma \leq \varepsilon \int_{\Omega} |v_0(x) - v_0^*(x)| dx + \lambda \int_{\Omega} |u_0(x) - u_0^*(x)| dx. \end{aligned} \quad (4)$$

In particular, if $u_0 = u_0^$ and $v_0 = v_0^*$ we conclude that $u = u^*$ and $v = v^*$.*

Idea of the proof. Some manipulations lead to

$$(u - u^*)_t + (f(u) - f(u^*))g(v^*) = -f(u)(g(v) - g(v^*)) \quad (5)$$

and

$$\varepsilon(v - v^*)_t - \Delta(v - v^*) + \lambda f(u)(g(v) - g(v^*)) = -\lambda g(v^*)(f(u) - f(u^*)). \quad (6)$$

By multiplying (5) by $\text{sign}_0(u - u^*)$ ($=1$ if $u - u^* > 0$, $=0$ if $u - u^* = 0$ and -1 otherwise) and by using property

$$\int_0^t \int_{\Omega} h_t \operatorname{sign}_0 h \, dx d\tau = \int_{\Omega} |h(t, x)| \, dx - \int_{\Omega} |h(0, x)| \, dx$$

which holds for any $h \in W^{1,1}(0, T; L^1(\Omega))$ (see e.g. [1], [2], [3]), we obtain

$$\int_{\Omega} |u - u^*| \, dx + \int_0^t \int_{\Omega} h(v^*) |f(u) - f(u^*)| \, dx d\tau \leq \int_{\Omega} |u_0 - u_0^*| \, dx + \int_0^t \int_{\Omega} f(u) |g(v) - g(v^*)| \, dx d\tau \quad (7)$$

Analogously, by multiplying (6) by $\operatorname{sign}_0(v - v^*)$ and by using that

$$-\int_{\Omega} \Delta(v - v^*) \operatorname{sign}_0(v - v^*) \, dx \geq -\frac{1}{\alpha} \int_{\partial\Omega} |v - v^*| \, ds$$

(which holds by regularization of $\operatorname{sign}_0(\cdot)$ and by applying Green's formula) we get

$$\begin{aligned} \varepsilon \int_{\Omega} |v - v^*| \, dx + \frac{1}{\alpha} \int_0^t \int_{\partial\Omega} |v - v^*| \, ds d\tau + \lambda \int_0^t \int_{\Omega} f(u) |g(v) - g(v^*)| \, dx d\tau \leq \\ \leq \varepsilon \int_{\Omega} |v_0 - v_0^*| \, dx + \lambda \int_0^t \int_{\Omega} g(v^*) |f(u) - f(u^*)| \, dx d\tau. \end{aligned} \quad (8)$$

By multiplying (7) by λ and adding (8) we obtain (4). \square

Remark 1. If we introduce the Banach space $E = L^1(\Omega) \times L^1(\Omega)$ with the norm

$$\|(u, v)\| = \varepsilon \|u\|_{L^1(\Omega)} + \lambda \|v\|_{L^1(\Omega)}$$

and if we denote by $S(t): E \rightarrow E$ the semigroup operator defined by

$$S(t)(u_0, v_0) = (u(\cdot, t), v(\cdot, t))$$

with (u, v) solution of P_{ε} , then Theorem 1 shows that $S(t)$ is a semigroup of contractions in E . The same type of argument (well-known in the framework of porous media equations [1], [6]) allows us to show that the operator $A: D(A) \subset E \rightarrow E$ defined by

$$A(u, v) = (f(u)g(v), -\frac{1}{\varepsilon} \Delta v + \frac{\lambda}{\varepsilon} f(u)g(v))$$

$$D(A) = \{(u, v) \in E: A(u, v) \in E\}$$

is accretive in E . In fact this property holds for a larger class of operators of the form

$$A(u, v) = (Au + f(u)g(v), Bv + \mu f(u)g(v))$$

where A and B are accretive operators in $L^1(\Omega)$. So, it is possible to apply to problem P_{ε} the results of the abstract theory of accretive operators (see e.g. [1], [2], [3]).

3. The pseudo-steady-state problem. Since the usual magnitude of ε is very small, specialists in chemical engineering very often replace problem P_{ε} by the so called pseudo-steady-state formulation.

$$P_0 \begin{cases} \bar{u}_t = -f(\bar{u})g(\bar{v}) & \text{in } Q_{\infty} \\ -\Delta \bar{v} = -\lambda f(\bar{u})g(\bar{v}) & \text{in } Q_{\infty} \\ \alpha \frac{\partial \bar{v}}{\partial n} = 1 - \bar{v} & \text{on } \partial\Omega \times (0, \infty) \\ \bar{u}(x, 0) = \bar{u}_0(x) & \text{on } \Omega. \end{cases}$$

where $\bar{v} = \bar{v}(x, t)$ and $\bar{u}_0 \in L^\infty(\Omega)$, $0 \leq \bar{u}_0 \leq 1$. We remark that no initial condition on \bar{v} is needed because $\bar{v}(x, 0) = \zeta(x)$ with $\zeta(x)$ determined as the (unique) solution of

$$\begin{cases} -\Delta \zeta &= -\lambda f(\zeta)g(\bar{u}_0) & \text{in } \Omega \\ \alpha \frac{\partial \zeta}{\partial n} &= 1 - \zeta & \text{on } \partial \Omega. \end{cases}$$

It is easy to see that the existence and continuous dependence results of §2 can be extended to problem P_ε .

Concerning the convergence as ε tends to zero of $(u_\varepsilon, v_\varepsilon)$, solution of P_ε , to (\bar{u}, \bar{v}) solution of P_0 we obtain in [11] results of a different nature:

(i) Monotone iteration and super-subsolution technique: Assuming $u_{0,\varepsilon}(x) \geq \bar{u}_0(x)$ and $v_{0,\varepsilon}(x) \leq \bar{v}_0(x)$ then $u_\varepsilon \searrow \bar{u}$ and $v_\varepsilon \rightarrow \bar{v}$ ($v_\varepsilon \leq \bar{v}$) uniformly in Q . If in addition

$$\begin{aligned} -\Delta v_{0,\varepsilon} + \lambda f(1)g(v_{0,\varepsilon}) &\leq 0 & \text{in } \Omega \\ v_{0,\varepsilon} - 1 + \alpha \frac{\partial v_{0,\varepsilon}}{\partial n} &\leq 0 & \text{on } \partial \Omega \end{aligned}$$

then $v_\varepsilon \nearrow \bar{v}$, uniformly in Q .

(ii) L^1 -estimates: Assume $\|u_{0,\varepsilon} - \bar{u}_0\|_{L^1} \leq C_1 \varepsilon^{(1+\alpha_1)}$ and $\|v_{0,\varepsilon} - \bar{v}_0\|_{L^1} \leq C_1 \varepsilon^{(1+\alpha_2)}$

($\alpha_1, \alpha_2 \geq 0$) then $\|u_\varepsilon(\cdot, t) - \bar{u}(\cdot, t)\|_{L^1} \leq \varepsilon(C_3 \varepsilon^{\alpha_1} + C_4 \varepsilon^{\alpha_2})$ and

$\|v_\varepsilon(\cdot, t) - \bar{v}(\cdot, t)\|_{L^1} \leq C_5 \varepsilon^{\alpha_1} + C_6 \varepsilon^{\alpha_2}$. (The proof uses the same type of arguments as in Theorem 1).

(iii) Estimates (independent of $v_{0,\varepsilon}$ and \bar{v}_0) in $L^1(0, t; C(\bar{\Omega}))$: Assume

$0 \leq \bar{u}_0 \leq u_{0,\varepsilon} \leq 1$, $0 \leq v_{0,\varepsilon} \leq \bar{v}_0 \leq 1$. Then for any $t > 0$

$$0 \leq \int_0^t (\bar{v}(x, \tau) - v_\varepsilon(x, \tau)) d\tau \leq \left\{ \varepsilon + \lambda \|u_{0,\varepsilon} - \bar{u}_0\|_{L^\infty} \right\} w(x) \quad \text{a.e. } x \in \Omega$$

and

$$0 \leq \int_\Omega (u_\varepsilon(x, t) - \bar{u}(x, t)) dx \leq \frac{\varepsilon |\Omega|}{\lambda} + \int_\Omega (u_{0,\varepsilon}(x) - \bar{u}_0(x)) dx,$$

where $w \in C^\infty(\Omega)$ is the unique solution of

$$\begin{cases} -\Delta w &= 1 & \text{in } \Omega \\ w + \alpha \frac{\partial w}{\partial n} &= 0 & \text{on } \partial \Omega. \end{cases}$$

(The idea of the proof is to integrate in time the equations of \bar{v} and v_ε and in x the ones of \bar{u} and u_ε). That extends previous results in [18] and [17].

4. On the solid conversion and the gas penetration.

Some particular examples show that if $f(s)=s^m$ with $0 < m < 1$ then the solid is partially converted for large time t and a free boundary $F(t)$ appears defined as the boundary of the *conversion region* of the solid $\Omega_0^u(t) := \{x \in \bar{\Omega} : u(x,t) = 0\}$. The following result gives a characterization of the functions f generating the free boundary $F(t)$.

Theorem 2. a) Assume $f(u)$ such that

$$\int_{0^+} \frac{ds}{f(s)} < \infty \tag{9}$$

Then $\Omega_0^u(t)$ is not empty for t large enough and in fact $\Omega_0^u(t) = \Omega$ after some suitable time t_0 .

b) If on the contrary

$$\int_{0^+} \frac{ds}{f(s)} = +\infty$$

then $u(x,t) > 0$ for any $x \in \bar{\Omega}$ and $t > 0$.

Idea of the proof. Define the auxiliary function

$$\theta(r) = \int_0^r \frac{ds}{f(s)}$$

Then it is easy to see that $u(x,t) = \theta^{-1}(\theta(u_0(x)) - \int_0^t g(v(x,\tau)) d\tau)$.

Finally as $v(x,t) \rightarrow 1$ if $t \rightarrow \infty$ and $\theta^{-1}(0) = 0$ we obtain the conclusion (a).

The proof of (b) uses a comparison argument. \square

We also introduce the **overall conversion at time t** by

$$\gamma(t) = \frac{\int_{\Omega} (u_0(x) - u(x,t)) dx}{\int_{\Omega} u_0(x) dx}$$

It is easy to see that $\gamma(t) \rightarrow 1$ as $t \rightarrow \infty$, and that if (9) holds then there exist a t_0 (called **full conversion time**) at which $\gamma(t_0) = 1$.

Theorem 3. Let $u_0 = 1$, $0 \leq v_0 \leq 1$, f satisfying (9) and g such that there exists g_1 and g_2 Lipschitz nondecreasing functions with $g_1(1) = g_2(1) = g(1)$ and satisfying $g_1(r) \leq g(r) \leq g_2(r) \forall r \in [0,1]$. Then we have the estimate

$$\frac{1}{g(1)} (I + M_2 \lambda \|w\|_{L^\infty}) \leq t_0 \leq \frac{1}{g(1)} (I + M_1 \lambda \|w\|_{L^\infty})$$

where $I = \theta(1)$, $M_1 = \sup\{g_1(r) : r \in [0,1]\}$, $M_2 = \inf\{g_2(r) : r \in [0,1]\}$.

We shall not give the proof of this result but we point out an interesting application to the case of $g(v) = v^p$, $p > 0$: (i) If $p = 1$ then $t_0 = I + \lambda \|w\|_{L^\infty}$ (Sohn-Szekely law of additive times); (ii) If $p < 1$ then $I + p\lambda \|w\|_{L^\infty} \leq t_0 \leq I + \lambda \|w\|_{L^\infty}$; (iii) If $p > 1$, $I + \lambda \|w\|_{L^\infty} \leq t_0 \leq I + p\lambda \|w\|_{L^\infty}$. Similar results holds for the pseudo-steady-state problem. These results generalize the ones of [19] and [17].

Finally another free boundary may occur as the boundary of the gas penetration region $\Omega_0^v(t) = \{x \in \Omega : v(x,t) \neq 0\}$.

Theorem 4. Assume g such that

$$\int_{0^+} \frac{ds}{\sqrt{G(s)}} < \infty, \quad G(s) := \int_0^s g(r) dr.$$

Then for any $t > 0$ there exists $C(t) > 0$ such that

$$\Omega_0^v(t) \supset \{x \in \Omega - \text{supp } v_0 : d(x, \text{supp } v_0) \geq C(t)\}.$$

On the other hand, if

$$\int_{0^+} \frac{ds}{\sqrt{G(s)}} = +\infty$$

then $v(x,t) > 0$ for any $t > 0$ and $x \in \bar{\Omega}$.

The proof uses some results in the literature (see [4],[5],[7],[8],[9],[10]). We refer the reader to [11] for details and other additional results.

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