

## ON THE BOUNDARY LAYER FOR DILATANT FLUIDS

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### 1 Introduction: the boundary layer and the von Mises transformation.

This paper deals with the boundary layer associated to a class of non Newtonian fluids, i. e., fluids for which the stress tensor  $\mathbf{T}$ , at given temperature and pressure, is not a linear function of the spatial variation of the velocity  $\mathbf{L} \doteq \nabla \mathbf{v}$ . This class of fluids is relevant in many contexts: chemical engineering (polymer melts, polymer solutions, suspensions, lubricants, paints, etc.), liquid crystals, oriented media, fibrous media, animal blood etc. (see, e. g., Schowalter [28] and Narasimhan [17]). The above notion of non-Newtonian fluids fails to bound the subject. An important subclass is the so called *purely viscous non-Newtonian fluids*. To introduce this notion we start from the *Reiner-Rivlin principle of material objectivity*

$$\mathbf{T} = -P\mathbf{I} + \phi_1(I_1, I_2)\mathbf{D} + \phi_2(I_2, I_3)\mathbf{D}^2,$$

where  $P$  is the pressure,  $\mathbf{I}$  is the identity tensor and  $I_i$  ( $i = 1, 2, 3$ ) are the principal invariants of  $\mathbf{D} \doteq \frac{1}{2}(\nabla \mathbf{v} + \nabla \mathbf{v}^T)$ , the symmetric part of  $\mathbf{L}$ . The special case of  $\phi_1$  identically constant and  $\phi_2 = 0$  corresponds to the case of incompressible Newtonian fluids. The more general case of  $\phi_2 = 0$  and non-constant  $\phi_1$  defines

the class of purely viscous non Newtonian fluids (also called generalized Newtonian fluids). It is useful to introduce the *shear stress* function

$$\tau(\kappa) = \frac{1}{2}\phi_1(\kappa)\kappa$$

where  $\kappa$  represents the *shear rate*. The *Power-law* or *Ostwald-de Waele model* is the one associated to the case of

$$\tau(\kappa) = K|\kappa|^{p-2}\kappa.$$

where  $p > 1$  is given as a constitutive property of the fluid. If  $p = 2$  we find again the class of Newtonian fluids. The case of  $p > 2$  corresponds to the so called *dilatant fluids* and the case  $1 < p < 2$  to the *pseudoplastic fluids*.

The Navier-Stokes system associated to a two-dimensional stationary flow of a incompressible dilatant fluid is

$$\begin{aligned} u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} &= -\frac{1}{\rho}\frac{\partial P}{\partial x} + \nu\frac{\partial}{\partial x}\left(|\mathbf{D}|^{p-2}\frac{\partial u}{\partial x}\right) + \frac{\nu}{2}\frac{\partial}{\partial y}\left(|\mathbf{D}|^{p-2}\left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}\right)\right) \\ u\frac{\partial v}{\partial x} + v\frac{\partial v}{\partial y} &= -\frac{1}{\rho}\frac{\partial P}{\partial y} + \frac{\nu}{2}\frac{\partial}{\partial x}\left(|\mathbf{D}|^{p-2}\left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}\right)\right) + \nu\frac{\partial}{\partial y}\left(|\mathbf{D}|^{p-2}\frac{\partial v}{\partial y}\right) \\ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} &= 0 \end{aligned}$$

where  $\mathbf{v} = (u,v)$  is the velocity, P the pressure,

$$\mathbf{D} = \begin{pmatrix} \frac{\partial u}{\partial x} & \frac{1}{2}\left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}\right) \\ \frac{1}{2}\left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}\right) & \frac{\partial v}{\partial y} \end{pmatrix}$$

and

$$|\mathbf{D}|^2 = u_x^2 + \frac{1}{2}(u_y + v_x)^2 + v_y^2.$$

In 1904, L. Prandtl [22] studied the influence of viscosity in a Newtonian flow at high Reynolds number in the presence of an obstacle. If we assume that the flow is exterior to a body (here represented by the interval  $(0,X)$  in the x-axes) and that a representative value of the modulus of the velocity is V, then the Reynolds number is  $R = \frac{VX}{\nu}$  (we can assume, for simplicity, that  $\rho \equiv 1$ ). The transition from zero velocity at the wall to the free stream velocity (velocity of the outer flow)  $(U(x),0)$  takes place in a very thin layer: *the boundary layer*. To study such a layer, Prandtl used some simplifications. For instance, it is natural to expect that

$$\frac{\delta}{X} \ll 1,$$

where  $\delta$  is the boundary layer thickness. It is not difficult to see that this property is equivalent to the condition

$$\left|\frac{\partial u}{\partial y}\right| \gg \left|\frac{\partial u}{\partial x}\right|.$$

Using dimensional analysis it can be shown that under this condition

$$\left| \frac{\partial P}{\partial y} \right| \ll 1.$$

So, following Prandtl, we can assume the Bernoulli equation for the outer flow to be

$$U(x) \frac{dU}{dx}(x) = -\frac{dP}{dx}(x).$$

Neglecting smaller terms, the Navier-Stokes system leads to the following problem:

$$(PS) \begin{cases} u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = UU_x + \nu \frac{\partial}{\partial y} \left( \left| \frac{\partial u}{\partial y} \right|^{p-2} \frac{\partial u}{\partial y} \right) & \text{in } Q, \\ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 & \text{in } Q, \\ u(0, y) = u_0(y) & y > 0, \\ u(x, 0) = 0, v(x, 0) = v_0(x) & x \in (0, X), \\ u(x, y) \rightarrow U(x) \text{ as } y \rightarrow \infty & x \in (0, X). \end{cases}$$

where  $Q \doteq \{(x, y) : 0 < x < X, 0 < y\}$ . In most physical problems  $v_0(x) \equiv 0$ ; nevertheless, the case  $v_0(x) \leq 0$  is also relevant in the so called *suction problems*. To study problem (PS), several reformulations are proposed in the literature. The key point is to work with the *stream function*  $\psi$  given by

$$\begin{cases} u = \frac{\partial \psi}{\partial y} \\ v = -\frac{\partial \psi}{\partial x} + v_0, \psi(x, 0) = 0 \end{cases}$$

Notice that the level lines of  $\psi$  coincide with the *current lines* of  $\mathbf{v} = (u, v)$ . The first mathematical treatment of (PS) is carried out by studying the third order ordinary differential equation satisfied by  $\psi$  (see Schlichting [27] for the case of Newtonian flows). The second possibility is to introduce the *von Mises transformation* [34]

$$\begin{aligned} \psi &= \psi(x, y) & \psi &\in (0, \infty), \\ w(x, \psi) &\doteq u^2(x, y) & x &\in (0, X). \end{aligned}$$

In this way, we arrive at the scalar problem

$$(P_w) \begin{cases} \frac{\partial w}{\partial x} - \nu \sqrt{w} \frac{\partial}{\partial \psi} \left( \left| \frac{\partial w}{\partial \psi} \right|^{p-2} \frac{\partial w}{\partial \psi} \right) + v_0 \frac{\partial w}{\partial \psi} - 2UU_x = 0 & x \in (0, X), \psi \in (0, \infty), \\ w(0, \psi) = w_0(\psi) & \psi \in (0, \infty), \\ w(x, 0) = 0 & x \in (0, X), \\ w(x, \psi) \rightarrow U^2(x) & \text{as } \psi \rightarrow \infty, \end{cases}$$

where  $w_0(\psi)$  is defined through  $u_0(y)$ . The P.D.E. appearing in  $(P_w)$  is a nonlinear degenerate parabolic equation in which the  $x$  variable plays the role of *time* and  $\psi$  stands for the spatial variable. Some existence and uniqueness results for this

problem are due to Oleinik [18], [19] (case of  $p = 2$ ) and Samokhin [26] (case of  $p > 2$ ). The assumptions of those papers are the following:

$$\begin{aligned} U(x) &> 0 && \text{for } x \in (0, X), \\ u_0(0) &= 0 \text{ and } u_0(y) > 0 && \text{for } y > 0, \\ u_0'(0) &= 0, (u_0', u_0'') \in L^\infty(0, \infty)^2 \\ U(0)U_x(0) - v_0(0)\frac{du_0}{dy} + \nu \left| \frac{du_0}{dy} \right|^{p-2} \frac{d^2u_0}{dy^2} &= 0(y^2) \quad (\text{consistency condition}). \end{aligned}$$

We also mention the results by Oleinik [19], Serrin [29] and Peletier [21] on the asymptotic behavior when  $X = +\infty$ .

## 2 The results

The main goal of this work is to study the *coincidence set*

$$\{(x, \psi) : w(x, \psi) = U^2(x)\}$$

for the case of dilatant fluids. The boundary of this region could be called the *exact boundary layer*.

**Remark 1** By the weak maximum principle, it is well known that necessarily  $w(x, \psi) \leq U^2(x)$  in  $(0, X) \times (0, \infty)$ . In fact, if  $p = 2$ , it can be shown (see Oleinik [19]) that the strong maximum principle also holds and thus  $w(x, \psi) < U^2(x)$  in  $(0, X) \times (0, \infty)$ , i. e. the coincidence set is empty. We recall that there are several attempts to make the boundary layer concept more precise. For instance, in Schlichting [27] it is defined as the zone where  $u=0$ . We must mention also the integral method introduced by von Karman [33] in order to estimate the boundary layer thickness  $\delta$ .

Our main results are the following

**Theorem 1** (Existence of the coincidence set).

Assume  $p > 2$ ,  $v_0(x) \leq 0$ , and there exists  $\psi_0 \in (0, \infty)$  such that  $w_0(\psi) = U^2(0)$  for any  $\psi \geq \psi_0$ ; Then there exists  $C > 0$  and  $\mu \in (0, 1)$  such that

$$w(x, \psi) = U^2(x) \text{ for any } (x, \psi) \text{ such that } \psi \geq \psi_0 + Cx^\mu.$$

**Theorem 2** (Waiting distance along a streamline)

Assume  $p > 2$ ,  $v_0(x) \leq 0$  and that there exists  $\psi_0 \geq 0$ ,  $C > 0$  and  $\sigma \in (0, 1)$  such that,

$$\int_{\psi}^{\infty} (U^2(0) - w_0(\tau))^2 d\tau \leq C(\psi_0 - \psi)_+^{\sigma/(1-\sigma)}$$

for any  $\psi \in (\psi_0 - \varepsilon, +\infty)$ .

Then, there exists  $x_0 \in (0, X)$  such that

$$w(x, \psi_0) = U^2(x) \text{ for any } x \in [0, x_0].$$

**Sketch of the proof of Theorem 1.** It is based on a general *Energy Method* first introduced by one of the authors [1] and later improved and developed in [2], [3], [4], [5], [6], [7], [8], [9], [11], [12], [13], [14], [15], [16], [20] and [30] (see also [10], [23], [24], [31] and [32]).

*First step.* We introduce the homogenized unknown

$$z(x, \psi) \doteq U^2(x) - w(x, \psi).$$

We remark that by the comparison principle  $z(x, \psi) \geq 0$  on  $(0, X) \times (0, \infty)$ . We also point out that arguing as in [18], or [26], it is possible to obtain the *a priori estimate*

$$0 < C_1 \leq U^2(x) - z(x, \psi) \leq C_2 \text{ for any } x \in (0, X), \psi \in (0, \infty),$$

for some constants  $C_1 \leq C_2$ . On the other hand, it is easy to see that  $z$  satisfies

$$(P_z) \begin{cases} \frac{\partial z}{\partial x} - \nu \sqrt{U^2 - z} \frac{\partial}{\partial \psi} \left( \left| \frac{\partial z}{\partial \psi} \right|^{p-2} \frac{\partial z}{\partial \psi} \right) + v_0 \frac{\partial z}{\partial \psi} = 0 & x \in (0, X), \psi \in (0, \infty), \\ z(0, \psi) = U^2(0) - w_0(\psi) & \psi \in (0, \infty), \\ z(x, 0) = U^2(x) & x \in (0, X), \\ z(x, \psi) \rightarrow 0 & \text{a.s. } \psi \rightarrow \infty. \end{cases}$$

We remark that  $z(x, \psi) = 0$  on the coincidence set.

*Second step: Integration by parts formula.* We introduce the one-parameter energy domain

$$Q_\rho = (0, x) \times (\rho, \infty)$$

where  $\rho \geq \psi_0$  is arbitrary. Multiplying by  $z$  and by integrating (formally) by parts we obtain that

$$\begin{aligned} & \frac{1}{2} \int_\rho^\infty z^2(x, \psi) d\psi + \int_0^x \int_\rho^\infty \theta(s, \psi) \left| \frac{\partial z}{\partial \psi}(s, \psi) \right|^p ds d\psi + \\ & \frac{1}{2} \int_0^x (-v_0(s) z^2(s, \rho)) ds = \frac{1}{2} \int_\rho^\infty z^2(0, \psi) d\psi - \int_0^x \sqrt{wz} \left| \frac{\partial z}{\partial \psi} \right|^{p-2} \frac{\partial z}{\partial \psi} \Big|_{\psi=\rho} ds \end{aligned}$$

where

$$\theta(x, \psi) \doteq \frac{2U^2(x) - 3z(x, \psi)}{2\sqrt{U^2(x) - z(x, \psi)}}.$$

It is easy to see that

$$0 < C_3 \leq \theta(x, \psi) \leq C_4 \text{ for any } x \in (0, X), \psi \in (0, \infty).$$

*Third step.* We introduce the *energy functions*

$$b(x, \rho) \doteq \text{ess sup}_{0 \leq s \leq x} \frac{1}{2} \int_\rho^\infty z^2(x, \psi) d\psi$$

$$E(x, \rho) \doteq \int_0^x \int_\rho^\infty \theta(s, \psi) \left| \frac{\partial z}{\partial \psi}(s, \psi) \right|^p ds d\psi.$$

Applying the Holder inequality, we get that

$$\left| \int_0^x \sqrt{wz} \left| \frac{\partial z}{\partial \psi} \right|^{p-2} \frac{\partial z}{\partial \psi} \Big|_{\psi=\rho} ds \right| \leq C_5 \left( -\frac{\partial E}{\partial \rho}(x, \rho) \right)^{\frac{p-1}{p}} \left( \int_0^x |z(s, \psi)|^p ds \right)^{\frac{1}{p}}.$$

Now we need a technical result

**Lemma 3** (Trace-interpolation inequality, [16]). *Let  $\sigma \in (0, 1)$  be given by  $\sigma = (p+2)/3p$ . Then*

$$\left( \int_0^x |z(s, \psi)|^p ds \right)^{\frac{1}{p}} \leq C_6 x^{(1-\sigma)/p} (E^{1/p} + x^{1/p} b^{1/2})^\sigma b^{(1-\sigma)/2}.$$

**End of the proof of Theorem 1.** By using the above inequalities we can find an exponent  $\mu \in (0, 1)$  and a positive constant  $C_7$  such that

$$E^\mu \leq (E + b)^\mu \leq C_7 x^{(1-\mu)/(p-1)} \left( -\frac{\partial E}{\partial \rho}(x, \rho) \right).$$

This inequality implies the conclusion due to the following easy result

**Lemma 4** ([1]) *Let  $y \in C([0, t_1] \times [0, \rho_0 + \delta])$ ,  $y \geq 0$  such that*

$$\Phi(y(t, \rho)) \leq C t^\omega \frac{\partial y}{\partial \rho}(t, \rho)$$

*for a. e.  $\rho \in [0, \rho_0 + \delta]$  and for any  $t \in [0, t_1]$ , where  $\omega \geq 0$  and  $\Phi$  is a continuous nondecreasing function such that  $\Phi(0) = 0$  and*

$$\int_{0+} \frac{ds}{\Phi(s)} < \infty.$$

*Then there exists  $t_0 \in (0, t_1]$  and a function  $\rho(t)$  with  $0 \leq \rho(t) \leq \rho_0 + \delta$  such that  $y(t, \rho) = 0$  for any  $t \in [0, t_0]$  and any  $\rho \in [0, \rho(t)]$ .*

**Remark 2** A different proof of Theorem 1, based upon the comparison principle, and under additional conditions, is due to [26].

**Idea of the proof of Theorem 2.** Using the same type of arguments and the assumption at  $x = 0$  we obtain the differential inequality

$$E^\mu \leq C_7 x^{(1-\mu)/(p-1)} \left( -\frac{\partial E}{\partial \rho}(x, \rho) \right) + C_8 (\psi_0 - \psi)_+^{\mu/(1-\mu)}$$

for any  $\psi \in (\psi_0 - \varepsilon, +\infty)$ . The conclusion comes now from an analysis of this differential inequality

Lemma 5 ([2]) Let  $y \in C([0, t_1] \times [0, \rho_0 + \delta]), y \geq 0$  such that

$$\Phi(y(t, s)) \leq Ct^\omega \frac{\partial y}{\partial \rho}(t, s) + G((\rho - \rho_0)_+)$$

for a. e.  $\rho \in [0, \rho_0 + \delta]$  and for any  $t \in [0, t_1]$ , where  $\omega \geq 0$  and  $\Phi$  is as in Lemma 4 and

$$\exists \mu > 0 \text{ and } \varepsilon > 0 \text{ such that } G(s) \leq \varepsilon \Phi(\eta_\mu(s)), \text{ a.e. } s \in (0, \rho)$$

with

$$\eta_\mu(s) = \Theta_\mu^{-1}(s), \quad \Theta_\mu(\tau) = \int_{0^+}^{\tau} \frac{ds}{\mu \Phi(s)}.$$

Then there exists  $t^* \in (0, t_1]$  such that  $y(t, \rho) = 0$  for any  $t \in [0, t^*]$  and any  $\rho \in [0, \rho_0]$ .

**Remark 3** In the case of pseudo-plastic fluids ( $1 < p < 2$ ), it is possible to apply another kind of energy method (now using a suitable global energy) which leads to a different estimate on the location of the exact boundary layer: if  $X$  is large enough and  $U(x) \equiv 0 \forall x \geq x_U$  for some  $x_U > 0$ , then there exists  $x_0 \geq x_U$  such that  $w(x, \psi) = U^2(x) = 0, \forall x \geq x_0, \forall \psi \in (0, \infty)$  (see also [25]).

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